External Human-Machine Interface Design for Automated Vehicles Based on Analytic Hierarchy Process

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ABSTRACT

This research provides a theoretical basis and guidance for the design by establishing a demand index system for the external human-machine interface for automated vehicles. First of all, starting from literature research, combined with market product analysis and user interviews, to establish functional demand indicators for the design of external human-machine interface, then collect data through user surveys, and calculate through AHP to obtain the weights of each level and each element. Clarify the preference characteristics of each demand and carry out consistency test to establish an evaluation system to provide a basis for subsequent decision-making and design practice. Finally, combining the research conclusions and design practice, an external human-machine interface for automated vehicles is designed that meets the user's preferences and characteristics, and provides a usable and effective interface for pedestrians.

Keywords: Automated vehicles, External human-machine interface, Analytic hierarchy process

INTRODUCTION

With the development of technology and economy, the technology of automated vehicles is becoming more and more mature, and its research on perception, decision-making and control theory is advancing in an all-round way, and it is expected to play an important role in the future transportation system (Wu, C. Z. et al., 2018). Automated vehicles can perform driving tasks in road environments that human drivers can handle through the vehicle's own software and hardware, and the driver's attention is diverted to non-driving tasks such as office and entertainment (Tan, H. , and Zhao, Y., 2018). Therefore, automated vehicles need to transmit crucial information to pedestrians through an external human-computer interface, so that pedestrians can accurately predict the next behavior of the car and take action. As a bridge of communication, the study of the external human-machine interface for automated vehicles is of great significance.

OVERVIEW OF EXTERNAL HUMAN-MACHINE INTERFACE FOR AUTOMATED VEHICLES

Human-computer interaction refers to the process of exchanging information between people and computers through a certain conversation language and interaction mode. Faced with the complex human-vehicle interaction environment, the design of the external human-machine interface for automated vehicles is an effective way to establish interaction between vehicles and pedestrians.

Academia and some manufacturers have conducted related research on the design of the external human-machine interface to solve the communication problem between autonomous vehicles and pedestrians. Swedish Semcon uses an anthropomorphic design approach on the radiator grille of the car to present the 'smile' in the external human-machine interface (Snyder J B., 2016). In Baidu-Hongqi L4 automated vehicle, the interface is projected in front of pedestrians through the front projection device. Lagerstrom and his team showed different modes of autonomous vehicles by studying the different states of LED strip (Lagström, T. and Malmsten Lundgren, V., 2016). Automotive intelligence is an inevitable trend, and user demands have also undergone tremendous changes with the application of technology. This paper will carry out the design practice from the user's point of view based on the analytic hierarchy process.

RESEARCH METHOD AND DESIGN PROCESS

In order to provide pedestrians with a usable and effective external humanmachine interface, it is necessary to conduct user and market demand surveys to clarify the element goals. The AHP is introduced to screen all the element targets. This method mainly calculates the weight value of each element through the weight coefficient, and sorts all elements with the importance as the priority, so as to complete the design decision (Tang, L. et al., 2019).

Overview of Analytic Hierarchy Process

AHP is a multi-criteria decision-making method proposed by Professor Thomas L. Saaty in the early 1970s. Analytic Hierarchy Process (AHP) combines qualitative textual expressions with quantitative numerical expressions, takes quantitative analysis as the guide, and uses mathematical models as tools to comprehensively evaluate limited data samples through quantitative methods, which can effectively avoid the subjective one-sidedness of the transformation of demands (Sirisawat, P. and Kiatcharoenpol, T., 2018).

Design Process Analysis of External Human-Machine Interface

First, by investigating target users and existing research cases, obtain indepth user needs and design elements. Then, combine the analytic hierarchy process to build a hierarchical structure model, and calculate the target weights of design elements. Finally, the design element objectives are screened, sorted and analyzed, and design practice is carried out. The design of the application process mainly includes the following five steps (see Figure 1).

Step 1. User demand	Step 2. Design elements	Step 3. Introducing the AHP method	Step 4. Design	Step 5. Design evaluation
Through market research, liter- ature analysis and in-depth user interviews, we capture users' expectations and real demands for interface design, and con- vert user language into design needs.	From the design point of view, classify and analyze the user re- quirements, complete the quali- tative analysis of the design de- mands, and determine the design elements.	The user needs are constructed into a hierarchical structure model and a judgment matrix is established, and then mathe- matical methods are used to quantify the design elements, so as to clarify the design goals.	Combine the calculation results to sort all the design elements, then complete the design ele- ment analysis, and carry out in- novative design practice based on this.	Finally, a professional evalua- tion and user feedback survey are carried out on the design scheme to verify the effective- ness of the design method.

Figure 1: Design process of external human-machine interface.

HIERARCHICAL DEMAND INDEX OF EXTERNAL HUMAN-MACHINE INTERFACE FOR AUTOMATED VEHICLES

The selection of the design elements of the external human-machine interface for automated vehicles is a collection of many factors such as multi-level, multi-factor, and multi-indicator design. In the selection of evaluation indicators, the elements of evaluation indicators are supplemented and screened through paper reading, case analysis, and collection of opinions from relevant experts and design practitioners (Li L. P. and Guo X. Y., 2020). Through the above analysis method, the hierarchical structure of the external humanmachine interface is finally determined as follows: 1 target layer, 6 first-level indicators and 24 second-level indicators (see Table 1).

Target layer: The general target of the hierarchical structure model is the hierarchical design requirements of the external human-machine interface.

First-level indicators: Extract B1-Position, B2-Technology, B3-Text, B4-Graphics, B5-Color, B6-Personification, a total of six types of design index elements as criteria-level evaluation elements.

Second-level indicators: According to the design elements of first-level indicators, it is divided into details, and a total of 24 second-level evaluation indicators C1-C24 are selected by KJ method to complete the qualitative analysis of structured requirements.

THE WEIGHT OF EACH DESIGN DEMAND ELEMENT IN AHP ANALYSIS HIERARCHY PROCESS

After constructing the index system, this research uses the analytic hierarchy process to analyze each indicator of design demands of the external humanmachine interface for automated vehicles through questionnaire survey and in-depth interview, calculates the weight value of each index, and completes the consistency test.

Construct Judgment Matrix and Calculate the Weight of Each Index

In this study, 50 potential users who participated in the user interview above were selected to participate in the index evaluation, and formed decision makers, including interface designers, related researchers and others. Using the 9-level scaling method in the AHP method as the evaluation scale, it enables users to compare the preferences of each element pairwise and quantify the assignment, which plays an important role in establishing a matrix and finding eigenvector values.

Target layer	First-level indicators	Secondary indicators
Design requirements for	B1-Position	C1-Top of car
External Human-machine		C2-Windshield
Interface		C3-Radiator grille
		C4-Side view of car
		C5-The surface of the road
	B2-Technology	C6-Projection
	0,	C7-Display
		C8-LED light strip
	B3-Text	C9-Please passing
		C10-No passing
		C11-About to start
		C12-Thanks
	B4-Graphics	C13-Pedestrian
	-	C14-Wait
		C15-Welcome
		C16-Accelerate
		C17-Pass through
	B5-Color	C18-Traffic color
		C19-Cyan-blue
		C20-White
		C21-blue
	B6-Personification	C22-Eye
		C23-Smiley
		C24-Anthropomorphic graphics

Table 1. Hierarchical function index of External Human-machine Interface.

Set judgment matrix A is as follows:

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{n1} & a_{n2} & \dots & a_{mn} \end{pmatrix}$$

Through the judgment matrix, the weight value of each index is the eigenvector corresponding to the maximum eigenvalue of the judgment matrix, and the sum-product method is used to calculate the weight value to obtain the comprehensive weight of the hierarchical demand index for the design of the external human-machine interface (see Table 2).

According to the weight value of the first-level indicators, the order of importance of the design of the external human-machine interface is B1-Position, B2-Technology, B5-Color, B4-Graphic, B3-Text, B6-Personification, that means users want to put the location and technology of the interface first, followed by factors such as color and graphics. According to the weight value of the secondary indicators, users have higher ratings for C3-Radiator grille, C7-Display, C9-Please passing, C13-Pedestrian, C18-Traffic color, C23-Smiley. At the same time, users have a low degree of recognition of elements such as C1-Top of car and C6-Projection.

Target layer	First-level indicators	Weight value	λmax	Secondary indicators	Weight value	λmax
Design	B1-Position	0.452	6.509	C1-Top of car	0.035	5.243
requirements				C2-Windshield	0.134	
for External				C3-Radiator grille	0.503	
Human-				C4-Side view of car	0.068	
machine Interface				C5-The surface of the road	0.260	
	B2-	0.246		C6-Projection	0.106	3.039
	Technology			C7-Display	0.633	
				C8-LED light strip	0.261	
	B3-Text	0.047		C9-Please passing	0.416	4.081
				C10-No passing	0.312	
				C11-About to start	0.157	
				C12-Thanks	0.109	
	B4-	0.083		C13-Pedestrian	0.471	5.147
	Graphics			C14-Wait	0.142	
				C15-Welcome	0.068	
				C16-Accelerate	0.038	
				C17-Pass through	0.281	
	B5-Color	0.144		C18-Traffic color	0.647	4.034
				C19-Cyan-blue	0.101	
				C20-White	0.195	
				C21-blue	0.057	
	B6-	0.027		C22-Eye	0.193	3.046
	Personificati	on		C23-Smiley	0.496	
				C24-	0.310	
				Anthropomorphic graphics		

 Table 2. Comprehensive weight of hierarchical function index for External Humanmachine Interface.

Consistency Check

In order to avoid subjects being influenced by subjective factors, the data are now checked for consistency. To check the consistency of matrix A, the formula is:

$$C.R. = C.I./R.I.$$

R.I. values can be found online, and the C.I. numerical formula is:

$$C.I. = (\lambda_{max} - n)/(n - 1)$$

The C.R. value can be calculated from the above two formulas. When C.R.<0.1, it means that the calculation result of the matrix has passed the consistency test, and the calculated weights are consistent. The calculation results are shown in the table (see Table 3).

Target layer	First-level indicators	C.I.	C.R.	Secondary indicators	C.I.	C.R.
Design requirements for External Human-machine Interface	B1-B6	0.102	0.081	C1-C5 C6-C8 C9-C12 C13-C17 C18-C21 C22-C24	0.061 0.019 0.027 0.037 0.011 0.023	0.037 0.030 0.033 0.013

Table 3. Consistency test of external human-machine interface

It can be seen from the table that the consistency test of the judgment matrix satisfies C.R.<0.1, and the consistency test is passed.



Figure 2: Design of external human-machine interface for automated vehicles.

DESIGN PRACTICE OF EXTERNAL HUMAN-MACHINE INTERFACE

Design Practice

According to the weight analysis results of the design elements of the external human-machine interface for automated vehicles, using the basic process and methods of interface design, combining the research conclusions with practice, a human-machine interface outside the car is designed to provide a usable interface for pedestrians. This study applied the design to the smiling car concept of the Semcon Inc, as shown in the figure (see Figure 2).

In terms of location, the interface is selected at the C3-Radiator grille, which is more convenient for pedestrians to obtain the information to be conveyed by the car. In terms of technology, the interface is displayed in the form of C7-Display, which can realize more possibilities for interaction with pedestrians and realize more diversified information transmission. In terms of color, the interface adopts the standard color of C18-Traffic color, where red means stop and green means go, which is in line with the basic cognition of pedestrians, and enables pedestrians to produce higher accuracy and faster response (Kandil, F. I. et al., 2017). In terms of graphics, the interface adopts the graphics of C13-Pedestrians, combined with the graphics of crosswalks and pedestrians, which can more effectively convey the passable or impassable information to pedestrians and avoid confusion. In terms of text, the interface chooses the expression C9-Please passing and C10-No passing, if only a smile is used as an anthropomorphic expression, pedestrians always

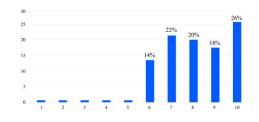


Figure 3: User NPS score results.

do not know whether to cross the road (Deb, S. et al., 2018). The combination of text and graphics can improve the interactive comfort of pedestrians and improve cognitive efficiency.

Design Evaluation

In order to improve the interface design of this time, it is necessary to conduct a user feedback test on the degree of achievement of user demand elements. In this test, the 50 members of the expert group mentioned above were invited to conduct a satisfaction test for the degree of achievement of the design demands. Taking the NPS value as the scoring standard, the horizontal axis is the score, and the vertical axis is the number of people (see Figure 3). The total NPS score is 30 after statistics, indicating that this scheme is a successful design practice.

CONCLUSION

Based on the AHP, this paper explores and studies the external humanmachine interface for automated vehicles, mainly through the process of case analysis, user research, demand analysis, weight calculation, etc., and finally carries out the design practice with the user needs as the leading factor. This study improves the usability and user satisfaction of the design to a certain extent, and the study method and process provide a certain degree of reference for the field. Due to the subjective evaluation test and the limited number of subjects in this study, there are certain limitations and deficiencies. In the future, we will consider combining advanced technology and more scientific methods to further study the external human-machine interface.

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