

Ergonomic Parameters Considering Physical Workload for Optimization Models in Manual Order Picking

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ABSTRACT

Order picking is a crucial contributor to corporate success within the value chain of companies. However, due to the high proportion of manual work, there is a risk of employees developing musculoskeletal disorders. In order to reduce this risk, it is vital to take ergonomics in planning concepts for order picking into account. For this purpose, ergonomic parameters are derived for picking from shelves and pallets in this paper on the basis of the EAWS screening method. The results are supported by data on postures and working conditions from practical surveys in four companies. The ergonomic parameters can subsequently be used in optimization models for order picking.

Keywords: Order picking, Physical workload assessment, EAWS, Warehouse, Optimization

INTRODUCTION

Order picking faces growing challenges. Increasing customer demands, such as enlarged product portfolios and shorter delivery times require efficient warehousing processes (Grosse et al., 2017). Order picking therefore has decisive influence on the company's success. Due to the complex and varying nature of order picking, the degree of automation is still rather low and manual work predominates (Michel, 2017). The numerous manual activities performed by order pickers, such as repeatedly lifting items in awkward postures, or pushing and pulling carts, increases the risk of developing musculoskeletal disorders (Marras et al., 1999). In fact, about 60% of the disease-related absenteeism of employees in the logistics sector are due to musculoskeletal disorders (Schneider et al., 2010). This underlines the importance to plan and manage order picking systems considering both the system's efficiency and the occurring physical workloads in a preventive manner (Grosse et al., 2015). To ensure efficient order picking, mathematical optimization is widely used in the literature. Among the most important

optimization problems are planning the warehouse layout (e.g. Diefenbach & Glock, 2019; Calzavara et al., 2017), assigning items to the storage locations (e.g. Steinebach et al., 2021a, Larco et al., 2017), routing the order pickers through the warehouse, and determining order batches.

To formulate suitable mathematical optimization models, ergonomic parameters are required to quantify the influence of certain manual handling activities on the order pickers' physical workload. Up to now, the literature has focused primarily on the workers' energy expenditure for that matter (e.g. Battini et al., 2016; Diefenbach and Glock, 2019). Others, as Larco et al. (2017), only considered the perceived exertion of employees. This paper develops a more sophisticated ergonomic quantification approach applying methods that are not only based on energetic but also on biomechanical and physiological studies, and that take several kinds of physical workload into account (e.g., manual material handling (MMH), static postures and upper limb loads in repetitive tasks). For this purpose, the well-established and well-suited screening method EAWS (Schaub et al., 2013) is proposed. The aim of this paper is to derive ergonomic parameters for the most relevant order picking activities (e.g., picking one-/two-handed from a pallet/a shelf) using EAWS 1.3.6 (www.eaws.it), which can subsequently be used in optimization models.

METHODS

EAWS quantifies workloads along four sections: static postures, action forces, MMH and repetitive loads of the upper limbs. In order picking, MMH is particularly relevant - however, each system must be analyzed individually regarding the other kinds of physical load. In parts-to-picker systems, for example, the upper limbs are subject to high workload due to repetitive activities (Wakula et al., 2021). In the following, we focus on MMH, whose risk factor (here called the "ergonomic parameter") is calculated as follows:

$$\text{Ergonomic Parameter} = (LP + PP + CP) \times DP$$

The Load Points (LP) result directly from the handled load weight according to EAWS, while the Posture Points (PP) depend on the working posture when the load is picked up or released. The PP depend, for example, on trunk flexion and twisting or the position of the load. The PP are between one and eight points according to EAWS. The Duration Points (DP; frequency of load manipulations) can range from 1 to 15 in EAWS. For our purpose, we set $DP = 1$ to obtain parameters for individual load manipulations. Otherwise, finding optimal solutions to the corresponding warehouse optimization problems is guaranteed to be intractable, which makes them virtually impossible to be solved optimally in realistic applications due to the very large number of evaluations that would be required. When pulling or pushing loads, additional Condition Points (CP) are also taken into account.

To obtain realistic data regarding the postures and working conditions, ergonomic analyzes were carried out in manually operated warehouses of four large companies in the industrial sector. Twelve different workplaces (with $n = 17$ subjects) in the picker-to-parts warehouse were analyzed using

the IMU motion capture system “Captiv”. The Captiv system was proven to generate valid joint angles to derive working postures with high accuracy in industrial contexts (Steinebach et al., 2020).

The workplaces were differentiated based on whether items were picked from pallets ($n = 422$ picks) or from shelves ($n = 509$ picks), and which equipment (forklift, pallet truck, handcart) was available to transport the items. Moreover, the observed picking tasks were differentiated by the weight and bulkiness of the items, handling patterns (e.g., one- or two-handed material handling) as well as the height of the lifting tasks’ origins and destinations. Finally, for each combination of characteristics, the observed data was averaged and evaluated using EAWS, such that the results apply for the single-time execution of the respective task. The results were summarized in a set of tables that differentiate between the tasks’ characteristics and the workers’ gender. The following focuses on picking from free-standing pallets on the floor as well as picking from shelves with different heights. The ergonomic parameters relating to the pallets are to be understood as mean values for different layers of the pallet depending on the maximum filling height. It is assumed that the items are released at a height of 90 cm, e.g., on a picking cart or a conveyor system.

RESULTS

The results of the posture analysis are shown in Figure 1. It indicates the PP as a function of the pick height of the pallet or shelf, respectively. The PP for picking from free-standing pallets are usually slightly higher than those for picking from a rack. The highest values (> 5 PP) result for very low pick heights. As the pick height increases, the PPs reach a minimum in a range between 1.0 and 1.2 m. Higher pick heights lead again to higher PPs due to the overhead work and larger distances of the load from the body. Picking from high pick heights results at a lower level than picking from very low pick heights.

In addition, the final ergonomic parameters for two-handed picking from racks or pallets, respectively, are presented in Tables 1 and 2. The tables distinguish between male and female order pickers and indicate parameters for different load weights (up to 20 kg). Analogous to the PP, the ergonomic parameters are lowest at medium pick heights. As expected, the parameters increase with higher load weights.

DISCUSSION AND CONCLUSION

The evaluation of the results shows that the ergonomic parameters depend primarily on the weight of the load and the postures adopted during MMH. This result is in line with the findings from the literature, e.g. Hanson & Medbo (2018), Skals et al. (2021) and Steinebach et al. (2021b).

The slightly higher PP when picking from pallets is due to the fact that the workers, on average, have to lean or bend further to reach the items. The different parameters for various pick heights demonstrate the potential to incorporate ergonomic considerations into optimization models, so

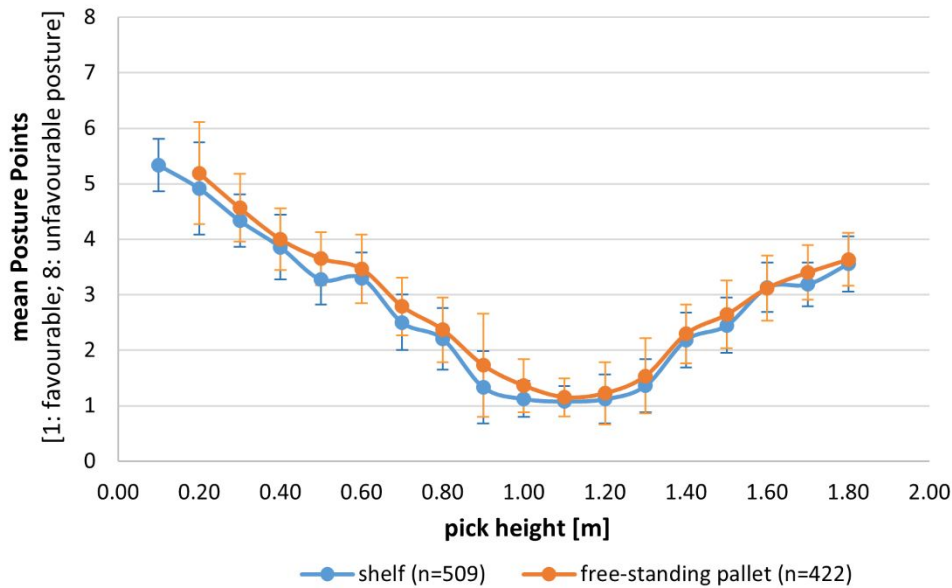


Figure 1: Mean Posture Points across all picking activities from shelves or free-standing pallets for different pick heights (standard deviations given via error bars).

that, for example, storing heavy or frequently required items at locations difficult to reach (and therefore high ergonomic parameters) is avoided. Moreover, the results may help planners to better evaluate the impact of different handling and design alternatives, such as technical equipment (lifting aids, height-adjustable carts), warehouse layouts, or routing strategies. By using appropriate optimization methods incorporating ergonomic parameters, the costs of appropriate measures can be compared with ergonomic and economic effects.

The ergonomic parameters presented here are an alternative to previously used approaches in optimization models, such as energy expenditure (Battini et al., 2016; Diefenbach & Glock, 2019) or compression forces on the spine (Steinebach et al., 2021b; Glock et al., 2019). The advantage of the developed ergonomic parameters is that not only individual criteria but combined biomechanical and physiological criteria as well as different kinds of workload based on EAWS are taken into account. In addition, the parameters are available for specific tasks in order picking, such as picking from shelves or pallets, which can be used directly by scientists or practitioners, if item properties, pick heights of the shelf or loading heights of the pallet are known.

It should be noted that the sum of the individual ergonomic parameters is not equivalent to an EAWS risk score. The parameters are only developed to solve ergonomic optimization models according to EAWS. Hence, it is recommended to carry out a risk assessment before and after optimization using the original EAWS method.

The results are subject to limitations, as the tables represent only certain handling patterns. One-handed picking can be considered according to EAWS

Table 1. Ergonomic parameters for lifting items from free-standing pallets (pallet on ground with max. loading height of 170 cm; two-handed lifting, non-bulky items).

		female																			
		Load weight [kg]																			
Loading height		3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20		
50 cm	3	3,84	4,01	4,18	4,43	4,68	5,01	5,34	5,68	6,18	6,68	7,18	7,68	8,18	8,48	8,78	9,08	9,38	9,68		
80 cm	3	3,53	3,69	3,86	4,11	4,36	4,69	5,03	5,36	5,86	6,36	6,86	7,36	7,86	8,16	8,46	8,76	9,06	9,36		
110 cm	3	3,18	3,35	3,51	3,76	4,01	4,35	4,68	5,01	5,51	6,01	6,51	7,01	7,51	7,81	8,11	8,41	8,71	9,01		
140 cm	3	3,03	3,19	3,36	3,61	3,86	4,19	4,53	4,86	5,36	5,86	6,36	6,86	7,36	7,66	7,96	8,26	8,56	8,86		
170 cm	3	3,06	3,22	3,39	3,64	3,89	4,22	4,56	4,89	5,39	5,89	6,39	6,89	7,39	7,69	7,99	8,29	8,59	8,89		

		male																			
		Load weight [kg]																			
Loading height		3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20		
50 cm	3	3,68	3,75	3,82	3,89	3,96	4,03	4,10	4,18	4,28	4,38	4,48	4,58	4,68	4,88	5,08	5,28	5,48	5,68		
80 cm	3	3,36	3,43	3,50	3,57	3,64	3,72	3,79	3,86	3,96	4,06	4,16	4,26	4,36	4,56	4,76	4,96	5,16	5,36		
110 cm	3	3,01	3,08	3,16	3,23	3,30	3,37	3,44	3,51	3,61	3,71	3,81	3,91	4,01	4,21	4,41	4,61	4,81	5,01		
140 cm	3	2,86	2,93	3,00	3,07	3,14	3,22	3,29	3,36	3,46	3,56	3,66	3,76	3,86	4,06	4,26	4,46	4,66	4,86		
170 cm	3	2,89	2,96	3,03	3,10	3,18	3,25	3,32	3,39	3,49	3,59	3,69	3,79	3,89	4,09	4,29	4,49	4,69	4,89		

by multiplying the actual weight of items by 1.7. In addition, some order picking systems may require parameters where the pallets are not stored free-standing on the floor. Similarly, bulky items or picking depths of over 40 cm when picking from shelves are not considered. The tables shown here are not applicable for such cases and would have to be adjusted. In the future,

Table 2. Ergonomic parameters for lifting items from shelves (storage depth < 40 cm; two-handed lifting, non-bulky items).

		female																			
Height	Load weight [kg]	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20		
		4.12	4.29	4.46	4.71	4.96	5.29	5.62	5.96	6.46	6.96	7.46	7.96	8.46	8.76	9.06	9.36	9.66	9.96		
20 cm		3.60	3.76	3.93	4.18	4.43	4.76	5.10	5.43	5.93	6.43	6.93	7.43	7.93	8.23	8.53	8.83	9.13	9.43		
40 cm		3.32	3.48	3.65	3.90	4.15	4.48	4.82	5.15	5.65	6.15	6.65	7.15	7.65	7.95	8.25	8.55	8.85	9.15		
60 cm		2.77	2.94	3.10	3.35	3.60	3.94	4.27	4.60	5.10	5.60	6.10	6.60	7.10	7.40	7.70	8.00	8.30	8.60		
80 cm		2.23	2.39	2.56	2.81	3.06	3.39	3.73	4.06	4.56	5.06	5.56	6.06	6.56	6.86	7.16	7.46	7.76	8.06		
100 cm		2.23	2.39	2.56	2.81	3.06	3.39	3.73	4.06	4.56	5.06	5.56	6.06	6.56	6.86	7.16	7.46	7.76	8.06		
120 cm		2.23	2.39	2.56	2.81	3.06	3.39	3.73	4.06	4.56	5.06	5.56	6.06	6.56	6.86	7.16	7.46	7.76	8.06		
140 cm		2.76	2.93	3.09	3.34	3.59	3.93	4.26	4.59	5.09	5.59	6.09	6.59	7.09	7.39	7.69	7.99	8.29	8.59		
160 cm		3.23	3.40	3.57	3.82	4.07	4.40	4.73	5.07	5.57	6.07	6.57	7.07	7.57	7.87	8.17	8.47	8.77	9.07		
180 cm		3.44	3.61	3.78	4.03	4.28	4.61	4.94	5.28	5.78	6.28	6.78	7.28	7.78	8.08	8.38	8.68	8.98	9.28		

		male																			
Height	Load weight [kg]	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20		
		3.96	4.03	4.10	4.17	4.24	4.31	4.39	4.46	4.56	4.66	4.76	4.86	4.96	5.16	5.36	5.56	5.76	5.96		
20 cm		3.43	3.50	3.57	3.64	3.71	3.79	3.86	3.93	4.03	4.13	4.23	4.33	4.43	4.63	4.83	5.03	5.23	5.43		
40 cm		3.15	3.22	3.29	3.36	3.44	3.51	3.58	3.65	3.75	3.85	3.95	4.05	4.15	4.35	4.55	4.75	4.95	5.15		
60 cm		2.60	2.67	2.75	2.82	2.89	2.96	3.03	3.10	3.20	3.30	3.40	3.50	3.60	3.80	4.00	4.20	4.40	4.60		
80 cm		2.06	2.13	2.20	2.28	2.35	2.42	2.49	2.56	2.66	2.76	2.86	2.96	3.06	3.26	3.46	3.66	3.86	4.06		
100 cm		2.06	2.13	2.20	2.27	2.35	2.42	2.49	2.56	2.66	2.76	2.86	2.96	3.06	3.26	3.46	3.66	3.86	4.06		
120 cm		2.59	2.66	2.74	2.81	2.88	2.95	3.02	3.09	3.19	3.29	3.39	3.49	3.59	3.79	3.99	4.19	4.39	4.59		
140 cm		3.07	3.14	3.21	3.28	3.35	3.42	3.49	3.57	3.67	3.77	3.87	3.97	4.07	4.27	4.47	4.67	4.87	5.07		
160 cm		3.28	3.35	3.42	3.49	3.56	3.63	3.71	3.78	3.88	3.98	4.08	4.18	4.28	4.48	4.68	4.88	5.08	5.28		

the development of ergonomic parameters for other kinds of physical load is promising. In particular, pulling or pushing of loads occurs regularly in order picking, e.g., pushing a picking cart. Depending on the system, upper limb loads due to repetitive tasks can also be relevant. This must be analyzed before evaluating or optimizing certain workplaces.

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