

# The Design of the Upper and Lower Limb Somatosensory Rehabilitation System Based on Users' Requirements

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## ABSTRACT

By exploring the requirements of the new elderly user group for upper and lower limb rehabilitation and guiding the design of the upper and lower limb somatosensory rehabilitation system based on the ranking of user requirements, the system is designed to meet the multi-level requirements of elderly users for autonomous rehabilitation training to a greater extent. Firstly, the user journey diagram and KJ method were used to sort out user requirement items. Based on this, the attribute categories of each requirement item were obtained by combining the Better-Worse method with the four-quadrant analysis using the Kano model. Finally, critical design requirements were identified by quantifying and ranking the importance of requirements based on AHP. By constructing the KJ-Kano-AHP design research model and combining it with the user journey map to analyze and quantify the importance of user requirements, this research provides direction and theoretical support for the design of upper and lower limb somatosensory rehabilitation systems. Additionally, it offers ideas for solving similar problems.

**Keywords:** User requirements, KJ, Kano, AHP, Limb rehabilitation, Somatosensory game

## INTRODUCTION

As the population ages, the incidence of stroke and other diseases is increasing. Clinical studies have shown that timely and effective rehabilitation training can significantly improve a patient's upper and lower extremity motor abilities. In contrast, general motor rehabilitation training usually requires patients to perform repetitive exercises for specific task-oriented training, which makes patients bored or lose interest in rehabilitation training, thus leading to a slower recovery rate (Hatem et al., 2016). To address this problem, research scholars have integrated rehabilitation games into motor intervention therapy to promote patients' motivation for rehabilitation training (Peña, Cibrian and Tentori, 2020). Nevertheless, existing studies have rarely considered the psychological and cognitive needs specific to the elderly population. Based on the Kano model and AHP theory, this study combines user journey diagram and KJ method to observe the influence of each user requirement on user satisfaction through Better-Worse four-quadrant

diagram, and quantitatively calculates the importance weight of user requirements to construct a user requirement importance ranking model to make reasonable design decisions.

## ACQUISITION OF UPPER AND LOWER LIMB SOMATOSENSORY REHABILITATION SYSTEM USER REQUIREMENTS

### Innovative Research Methods Based on the KJ-Kano-AHP Model

To accurately explore the needs of elderly patients for an upper and lower limb somatosensory rehabilitation system, this study conducted in-depth interviews and utilized user journey maps to analyze the users' process of using the product. Through this process, pain and opportunity points were discovered, and user requirements were obtained. The combination of the Kano model and analytic hierarchy process (AHP) quantified the user needs obtained from the research, and core design requirements were obtained. The research paper is divided into five steps (see Figure 1): First, identify user requirements based on the user journey map; Second, organize user requirements based on the KJ method; Third, screen user requirements based on the Kano model; Fourth, quantify user requirements based on the AHP method; Fifth, design output based on data conclusion. This innovative research method can help designers accurately identify key requirements and develop reasonable functional design solutions.

### Upper and Lower Limb Somatosensory Rehabilitation System User Journey Map Analysis

The study utilized the in-depth interview method to conduct extensive discussions with different groups, including rehabilitation patients, rehabilitation therapists, patients' family members, and nursing staff. The upper and lower limb somatosensory rehabilitation process was categorized into three main stages: the rehabilitation preparation phase, ongoing rehabilitation training phase, and end of rehabilitation phase. Based on the feedback obtained from the interviews, the users' behaviors and emotional experiences in each stage were organized, and pain points and opportunity points were identified and summarized in user journey maps (see Figure 2).

### Requirement Classification Model Based on the KJ method

The KJ method, also known as the affinity diagram method, is capable of classifying data inductively according to the correlation between different items

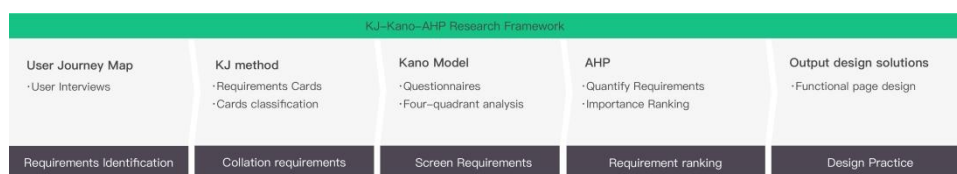


Figure 1: Research path.

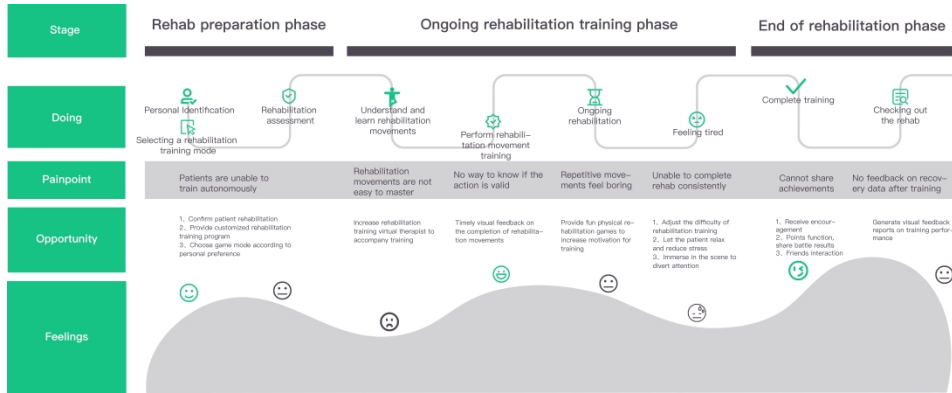


Figure 2: User journey map.

(Chen and Zhao, 2022). To address the problem of unclear and fragmented requirement points in user journey diagrams, this study distills user pain points and opportunity points into user requirements and uses the KJ method to organize and classify them. Firstly, the design team members organized and collected as much relevant user requirement information as possible, made the summarized 27 upper and lower limb somatosensory rehabilitation system requirement items into cards, and categorized them according to the similarity degree between each requirement item to obtain a preliminary classification model of upper and lower limb somatosensory rehabilitation game user requirements, which were divided into 4 categories in total: rehabilitation requirements, guidance requirements, game requirements, and social requirements(see Figure 3).

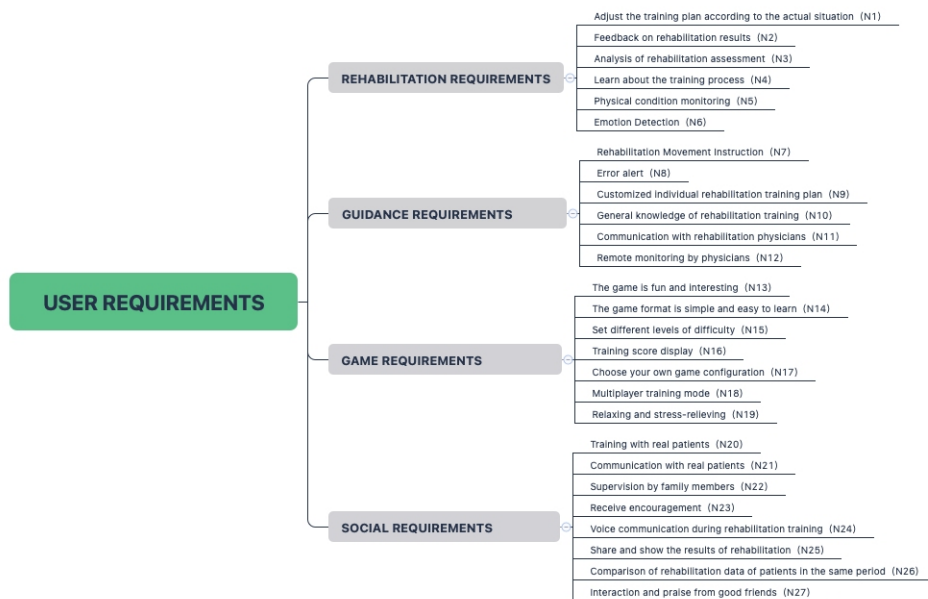


Figure 3: User requirements information.

## FURTHER FILTERING USER REQUIREMENTS BASED ON THE KANO MODEL

### Analysis of Kano Questionnaire Results

The research method was divided into the paper questionnaire and the electronic questionnaire. 113 valid questionnaires were collected from rehabilitation therapists, rehabilitation patients, patients’ families, and caregivers. The user data obtained from the questionnaires were collected and organized, and the impact of a certain demand item on user satisfaction and dissatisfaction was measured by calculating the satisfaction coefficient Better and the dissatisfaction coefficient Worse for each user demand item (Berger, Blauth and Boger, 1993). The specific formulas are (1) and (2).

$$Better = (A + O) \div (A + O + M + I) \tag{1}$$

$$Worse = (-1)(O + M) \div (A + O + M + I) \tag{2}$$

In the calculation, A indicates the number of charm demand options, O indicates the number of desired demand options, M indicates the number of essential demand options, and I indicates the number of undifferentiated demand options.

According to the calculation results of Better and Worse coefficients, the 27 user requirement items were divided into 4 essential requirements, 11 desired requirements, 5 charming requirements, and 7 non-differentiated requirements. The Better and Worse values are drawn to form a coordinate diagram which is the demand quadrant diagram (see Figure 4).

### Screening User Requirements Items Based on the Kano Model

The Kano model is applied to differentiate user satisfaction with different categories of product requirements, so the initial user requirements should be

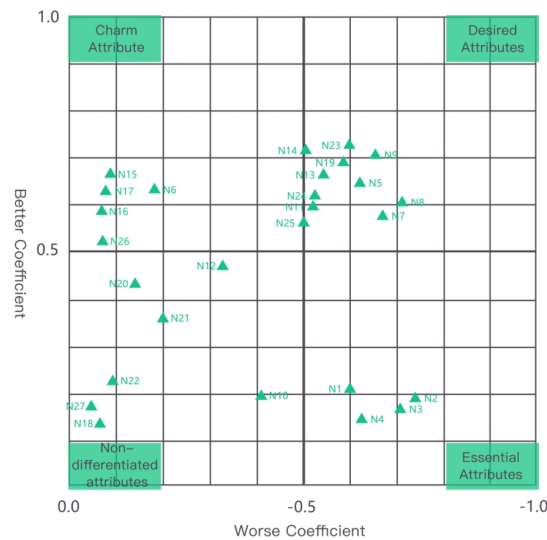
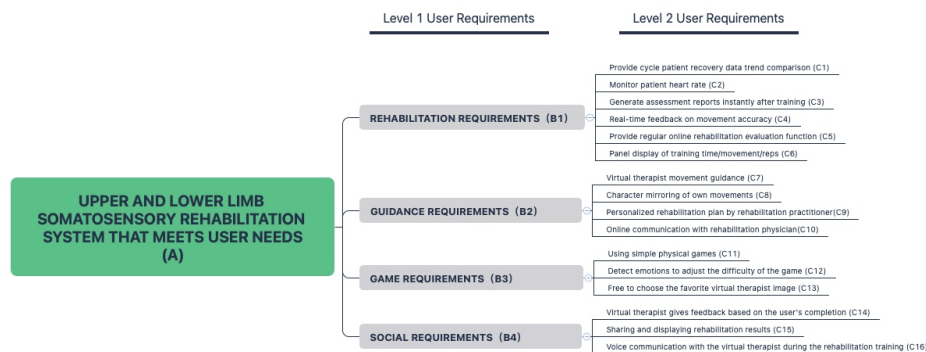


Figure 4: Demand attribute categorization quartile chart.

filtered according to the results of each requirement categorization in order to identify the user requirements more precisely (Yuan et al., 2021). In the Better-Worse requirements quadrature, for the “Essential attributes” requirements in the fourth quadrant, users consider that these requirements must be satisfied, and if they are not satisfied, they will feel very dissatisfied or even abandon the product; the requirements in the first quadrant are “Desired attribute” requirement, If the upper and lower limb somatosensory rehabilitation system includes the functional requirements in this area, the user’s satisfaction will be increased; for the second quadrant, the “Charm attribute” requirements are usually the requirements that the user is not aware of, if the product meets these requirements, the user’s satisfaction will be increased; while the “Non-differentiated attribute” requirement in the third quadrant is a product requirement that is not valued by users and has no impact on user satisfaction, so it is not necessary to consider this type of requirement too much in the actual design. After optimization, the hierarchical model of user requirements is formed (see Figure 5).



**Figure 5:** The hierarchical model of user requirements.

## QUANTIFYING USER REQUIREMENTS ITEMS BASE ON AHP

The analytic hierarchy process (AHP) is a combined qualitative and quantitative analysis research method that uses the method of solving the eigenvectors of the judgment matrix to obtain the priority weights of each layer element to the upper layer element (Luo and Li, 2021). The Kano model has certain superiority in analysing user requirements, but only qualitative analysis results can be obtained, and there is a certain subjective bias. Therefore, this study will improve user satisfaction of the upper and lower limb somatosensory rehabilitation system by combining the user requirements derived from the Kano model with the AHP method, which can quantitatively calculate the importance weights of the user requirements of the upper and lower limb somatosensory rehabilitation system for the design requirements.

### Demand Hierarchy Calculation Sorting

A total of 18 raters including upper and lower limb somatosensory rehabilitation therapists, patients, and designers scored the demand items of

the same tier in a two-by-two comparison and recorded them on the following scale  $x_i/x_j$ , with rating values as integers in the middle of 1-9, as a way to compare the degree of importance between the two elements and construct a judgment matrix for each tier.

In this study, the sum-product method was applied to calculate the ranking weights of each demand item, and the judgment matrix  $A$  was normalized by column to obtain matrix  $B = (b_{ij})_{n \times m}$ , as shown in equation (3). The matrix  $B$  normalized by column is summed for each row, see equation (4). The matrices  $A$ ,  $B_1$ ,  $B_2$ ,  $B_3$ ,  $B_4$  and the weights  $\omega_i$  are obtained (see Tables 1, 2, 3, 4, and 5).

$$b_{ij} = \frac{b_{ij}}{\sum_{k=1}^n b_{kj}} \quad (i, j = 1, 2, 3, \dots, n) \quad (3)$$

$$\omega_i = \sum_{j=1}^n b_{ij} \quad (i = 1, 2, 3, \dots, n). \quad (4)$$

### Consistency Verification of Judgment Matrix

The random consistency ratio  $CR$  is calculated and the formula is given in (5).

**Table 1.** Level 1 requirement items (B1-B4) judgment matrix  $A$  and weights.

A	B1	B2	B3	B4	$\omega_i$
B1	1	2	3	5	0.4575
B2	1/2	1	3	5	0.325
B3	1/3	1/3	1	3	0.15
B4	1/5	1/5	1/3	1	0.07

**Table 2.** Level 2 requirement items (C1-C6) judgment matrix  $B_1$  and weights.

A	C1	C2	C3	C4	C5	C6	$\omega_i$
C1	1	1/5	1/3	1/7	3	1/5	0.37
C2	5	1	2	1/2	5	1/2	1.16
C3	3	1/2	1	1/3	2	1/3	0.61
C4	7	2	3	1	5	2	1.97
C5	1/3	1/5	1/2	1/5	1	1/3	0.35
C6	5	2	3	1/2	3	1	1.36

**Table 3.** Level 2 requirement items (C7-C9) judgment matrix  $B_2$  and weights.

B2	C7	C8	C9	C10	$\omega_i$
C7	1	9	7	5	2.63
C8	1/9	1	1/2	1/5	0.22
C9	1/7	2	1	1/2	0.39
C10	1/5	5	2	1	0.77

**Table 4.** Level 2 requirement items (C11-C13) judgment matrix B3 and weights.

B3	C11	C12	C13	$\omega_i$
C11	1	3	5	1.9
C12	1/3	1	3	0.78
C13	1/5	1/3	1	0.32

**Table 5.** Level 2 requirement items (C14-C16) judgment matrix B4 and weights.

B4	C14	C15	C16	$\omega_i$
C14	1	1/3	1/7	0.28
C15	3	1	1/2	0.87
C16	7	2	1	1.86

**Table 6.** Random consistency ratio CR.

Judgment Matrix	Maximum characteristic root $\lambda$	CI	RI	CR
A	4.01	0.03	0.90	0.030
B1	6.35	0.07	1.24	0.056
B2	4.09	0.03	0.90	0.030
B3	3.06	0.03	0.58	0.051
B4	3	0	0.58	0

$$CR = \frac{CI}{RI} \quad (5)$$

If CR is less than 0.1, it means that the judgment matrix satisfies the consistency (Xi, Dong and He, 2019) and its data is reasonable, otherwise, there is no reasonable consistency, and it can be seen from the calculated results that CR is less than 0.01 (see Table 6), which means that the judgment matrix passes the consistency test.

### Calculation of Integrated Weight Value

By multiplying each weight value of the secondary user requirement item layer by the weight value of its corresponding primary requirement item layer, the comprehensive weight value of each requirement for the design of the upper and lower limb somatosensory rehabilitation system can be calculated (see Table 7).

## DESIGN PRACTICE BASED ON KJ-KANO-AHP MODEL

### Data Conclusions Based on Research Practices

Based on the overall weighting of user requirements, it is evident that the highest-ranking design requirements should be prioritized as key factors in designing an upper and lower limb somatosensory rehabilitation system. Specifically, design requirements such as “real-time feedback on movement

**Table 7.** Comprehensive weight value table.

	Level 1 User Require- ments	Weight value	Level 2 User Require- ments	Weight value	Combined weight value
upper and lower limb somatosensory rehabilitation system that meets user needs (A)	B1	0.4574	C1	0.37	0.169
			C2	1.16	0.531
			C3	0.61	0.279
			C4	1.97	0.901
			C5	0.35	0.160
			C6	1.36	0.622
	B2	0.325	C7	2.63	0.855
			C8	0.22	0.072
			C9	0.39	0.127
			C10	0.77	0.250
	B3	0.15	C11	1.9	0.285
			C12	0.78	0.117
			C13	0.32	0.048
	B4	0.07	C14	0.28	0.020
			C15	0.87	0.060
			C16	1.85	0.130

accuracy” (C4), “virtual therapist” (C7), “panel display of training time/movement/repetition” (C6), “instant evaluation report after training” (C3), “simple and common physical games” (C11), etc. were identified as priority design concerns. By prioritizing and optimizing these design requirements, the specific basis for designing an upper and lower extremity physical rehabilitation system was established, with the aim of addressing the core needs of upper and lower extremity rehabilitation patients and improving user satisfaction. Based on the results of the preliminary research, the design practice phase proceeded with the development of system modules, game content, and functional interfaces.

### Design Practice

In order to meet the rehabilitation needs of patients at different levels and effectively enhance their motivation for rehabilitation training, this study proposes a rehabilitation somatosensory game system, which consists of three main modules (see Figure 6): (1) somatosensory rehabilitation game module: based on mirror neuron rehabilitation therapy (Wu, Zeng and Wang, 2021), the rehabilitation training movements are designed as rehabilitation movement games based on somatosensory technology, which enables patients to use simple body movements to play (Lu, Ou and Ya, 2022), increasing the fun of rehabilitation training and testing the standard of patients’ rehabilitation movements in the process of the game. (2) Virtual assistant robot module: acts as a virtual therapist during the whole rehabilitation training process, guiding patients to perform correct rehabilitation exercises and providing real-time continuous feedback (see Figure 7). (3) Physiological signal recognition module: identifies the patient’s physical state based on the patient’s heart rate, and will suggest suspending the training when abnormal heart rate



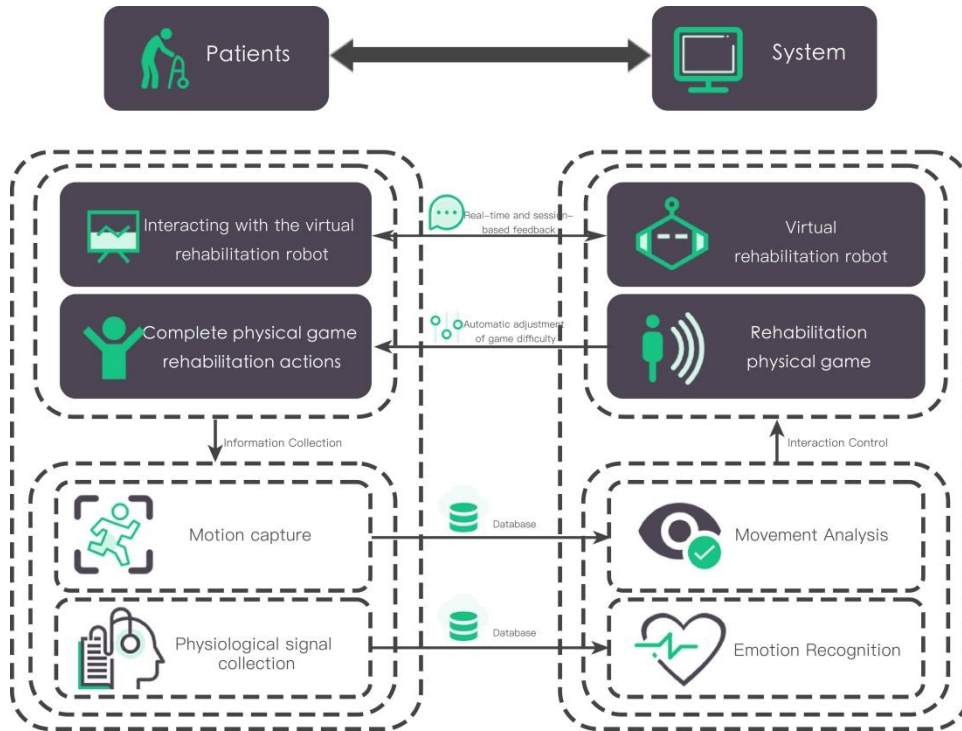


Figure 6: System architecture.

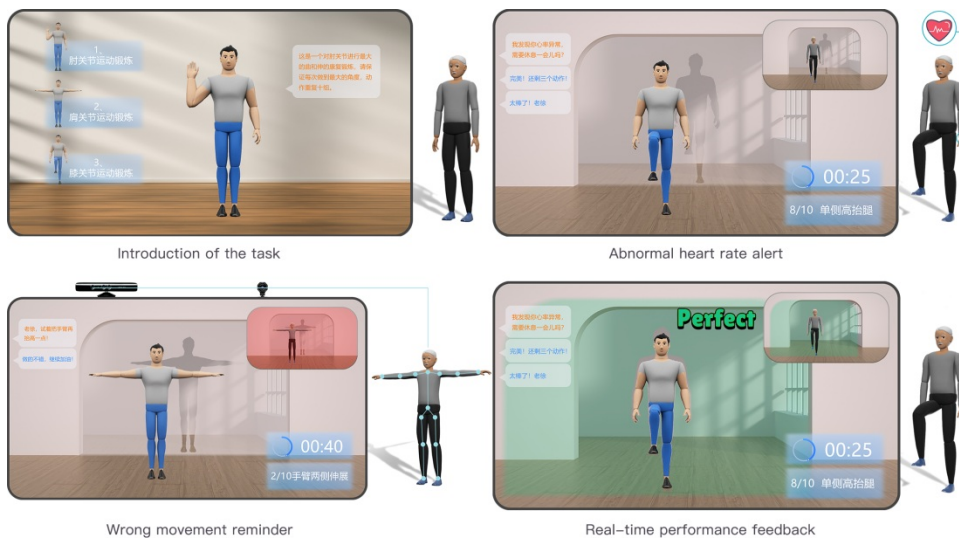


Figure 7: Virtual assisted therapist features page.

is monitored; identifies the patient’s emotional state based on the patient’s EEG signal data, and dynamically adjusts the game difficulty based on the patient’s emotion and performance to develop training tasks that are more suitable for the patient’s individual ability (see Figure 8).



**Figure 8:** Usage scenario diagram.

## CONCLUSION

In this study, quantitative research methods have been added to the qualitative analysis. During the user requirements acquisition stage, real user requirements are obtained using user journey maps and the KJ method. In the user requirements analysis stage, the Kano model is employed to qualitatively analyze the user requirements and classify them into attributes for easy screening. Finally, in the requirements determination stage, the AHP is used to quantify the requirements and rank their importance. This enables the identification of key design points more accurately and provides guidance for the design of the upper and lower limb somatosensory rehabilitation system.

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