

Ecological Collaborative Support System for Maritime Navigation Teams

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ABSTRACT

Collaboration within navy Navigation Teams is progressively more dependent on technological means since they are the information sources and team members need to share and exchange different information formats. Furthermore, operators' tasks are increasingly restricted by procedures established on information provided by various sources, constraining experts' feedback and learning. Moreover, interfaces are often poorly adapted to the user's task and work context, imposing a substantial cognitive effort due to the required adaptations. Therefore, the envisaged solution is fitted to the vessels' bridge systems requirements embracing prerequisites like being customisable, enabling goals and priorities' management, logging performance and behavioural data, sharing information, supporting information synchronisation, and providing situational awareness about the situation, system and operators.

Keywords: Bridge, Human factor, Human computer interface (HCI), Naval, Navigation

INTRODUCTION

Maritime navigation is a demanding and complex domain that involves risks for people, the environment, and economic activity. The tasks associated with its execution require advanced training, expertise, experience, and a collaborative Navigation Team. Furthermore, naval operations demand higher readiness, accuracy, and resilience due to additional constraints. The response to these challenges has been integrating further automation and information systems. However, the effectiveness of innovative trends had been questioned by recent naval accidents like those involving the US (US Department of the Navy and US Fleet Forces Command, 2017) and Norwegian naval ships (AIBN and DAIBN, 2019).

In bridge crews, collaboration is progressively more dependent on technological means since they are the information sources, and team members need to share and exchange different information formats besides audio. Furthermore, the increasing number of control functions and information systems required to strengthen the bridge situational awareness came with an additional cost to human operators. Therefore, navigation teams need further assistance in this challenging context to achieve a consistent and coherent situational awareness regarding the integrated systems in use, comprising

technological and human agents' activities (Christoffersen and Woods, 2002; Lützhöft and Dekker, 2002). The proposed solution under development is a Collaborative Decision Support System (C-DSS) fitted to the vessels' bridge systems requirements to reduce the cognitive workload, enhance collaboration between team members and information systems, and strengthen team situational awareness and sensemaking (Klein et al., 2004).

As the only controls are the ship's propulsion and steering systems, the bridge team need to appraise the vessels' navigation capability, including the navigation functions' performance and the interaction with environmental factors. The navigation functions are embedded in three navigation processes: forming goals, defining strategies and sailing (moving) (Conceição et al., 2018, p. 203). These processes require different cognitive skills, decision-making schemes and distributed cognition arrangements (Hutchins, 1995). The preparation and execution of a navigation plan have a relevant role in supporting the construction of shared mental maps (Klein et al., 2005). As found in other domains (Bearman et al., 2010), shared models also help to communicate intentions and needs with external actors, like other vessels, maritime authorities and services (van Westrenen and Praetorius, 2014).

The entire Bridge system has a combination and interaction of four articulated areas of concern: technical systems, human-computer interaction, human operator and operating procedures (Aarsæther and Moan, 2010). The workstations found in the bridges are linked to multiple systems and sensors. Team members interact within this environment of computerised tasks. In merchant ships, "Noise, proximity and layout provide a challenging interactional frame for situated action and navigational decision making" (Bailey, Housley and Belcher, 2006) while naval vessels, the much larger teams and operational constraints provide additional difficulties. Furthermore, machines' interfaces are often poorly adapted to the user's task and ever-changing context, imposing a substantial cognitive effort due to the required adaptations (Schager, 2008) and, consequently, deficient situational awareness (Endsley, 1995).

As human beings are not infallible, it is fundamental to consider organisational and technological issues (Hollnagel, 2009; Dekker, 2014). Unfortunately, the human-computer interaction is a significant weakness to solve, as oftentimes, the bridge is an aggregation of components that are developed as independent units, and also because it is complicated to constitute a sensitive bridge, both to environmental context and internal situation (Hadnett, 2008; Schager, 2008; Costa, 2018; Man et al., 2018). Moreover, mind biases and cognitive limitations emerge when judging under uncertainty (Água, Frias and Simões-Marques, 2021), which calls for new solutions to balance those effects. Finally, the provided working domain must not constrain human expertise, benefiting from intuition (Klein, 2003) and flexexecution processes (Klein, 2007).

The representation domain that each team member has, is driven by the interface being used, generating a diversity of interpretations (Hutchins, 1995). This variation that emerges from the complex distributed system

creates problems to resolve the situation (Bearman *et al.*, 2010). Socially distributed cognition requires a coordination mechanism to avoid misalignment of priorities and goals that are dynamically adjusted. Marquet (2018) identified the need for more resilient bridge crews where each team member keenly drives his actions based on the dynamic management of intentions. Collaboration becomes a valuable practice among individuals and between man and machine (Christoffersen and Woods, 2002).

Several studies addressed the need to provide enhanced interfaces with higher levels of abstraction representation, adjusted to the changed role of human operators, easily adaptable; improved collaboration between humans and automated agents, and superior information integration from internal and external environments. For example, Holder & Pecota (2011) suggest that a Head-Up Display could improve situation awareness in demanding situations where information changes rapidly, suggesting the potential to blend perceptual information into context and new standard information requirements. The OpenBridge project addresses user interfaces and sub-optimal workflows for navigators' inconsistencies, resulting from digitally integrated multivendor ship's bridges components, providing a repertoire of modern, intuitive and standardized tools (OpenBridge Design System, 2021). The European project CASCADE suggests new design methodologies that better integrate the human element through an adaptable bridge as a cooperative system (Javaux *et al.*, 2015). The result included a set of adaptive and shareable displays between elements and the integration of exceptional information, generally only available to the pilot, like sharing between the Portable Pilot Unit (PPU) and the ship's electronic charts. Other studies found advantages in sharing information with the PPU, as it improved early warning and faster navigational errors corrections (Rønningen and Øvergård, 2017). While working on a portable application to enhance information coordination and user experience to support river pilots for passing under bridges, Man *et al.* (2018, p. 222) concluded that users called for "a holistic system approach for interface design and system integration". In the naval domain, Hareide *et al.* (2017) designed a high-speed craft route monitor window to address navigators' workload, system awareness and human-system interaction.

A critical interfaces' requirement is simplifying the "discovery of the meaningfulness" of the problem space (Bennett and Flach, 2011, p. 26). Norman (1993, p. 52) proposes that the world's representation should include the relevant elements tailored to the task, augmenting the interaction experience, improving decision-making, and assisting the discovery of significant phenomena. In ecological interfaces, perceptions and actions should be harmonized, by implying the understanding of interventions consequences and intention realization (Bennett and Flach, 2011, p. 32). Ecological interface design should adopt a triadic perspective on cognition and display design, focusing on the working domain above the interpretation processes, with emphasis on "the pragmatic consequences of decisions, actions and the standards of comparison are based on the normative logic of dynamical systems" (Bennett and Flach, 2011, p. 453).

METHODS

Design Thinking was used as it is a method for developing products and services creatively and innovatively, involving the human being from the perception up to the solution (Dam, 2021). The process was performed with five commonly agreed-upon phases (Institute of Design at Stanford, 2010): Empathy, Definition, Idealisation, Prototyping and Test. Interface design prototypes were made with Balsamiq Mockups, version 4.1.2, covering the following roles: navigator, radar operator, chart operator and lookout. Usability tests, questionnaires and interviews were applied to verify and assess the C-DSS. Five focus group tests were made, with fifteen SMEs, twice with navigators, and once with SME from the other role, three in each iterative evaluation test. Following a snowball selection principle, participants were recruited from the Portuguese navy with an extensive seagoing experience. The questionnaire comprises two parts (see Figures 1 and 2): (1) general questions of UI and UX and, (2), specific contents applied to the work domain.

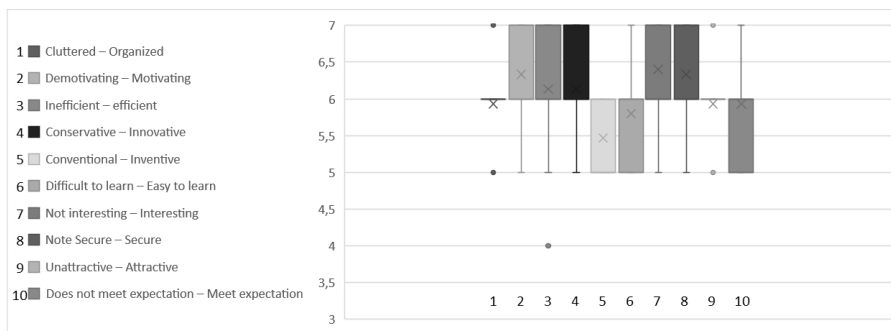


Figure 1: Box plot results of the UX questionnaires, part A.

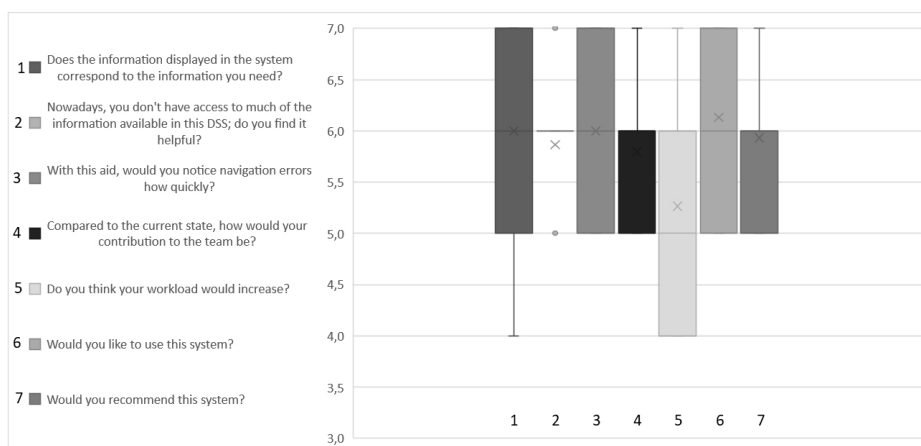


Figure 2: Box plot results of the UX questionnaires, part B.

Table 1. Menu of ideas.

	Collaborat	Perception	Cognitive workload	Proactivity
1. Changing the navigator's notebook by implementing more calculation aids.			?	
2. Changing the layout of the bridge.	?			
3. Reduction and standardization of information presented in displays.		?	?	
4. Creation of a device that integrates information from the various systems.		?	?	
5. Change in the standard procedure, decreasing verbal information exchange.	?			
6. Creation of an information-sharing device.	?			?
7. Implementation of events logs' analysis with feedbacks' sharing.	?			?
8. Creation of a device that assists team members' mental map.			?	?
9. Creating a common notebook framework. 10. Increasing the level of automation.	?		?	

RESULTS

The usability test corrected and improved numerous user interface design issues. As a possible solution, it was considered the possibility of C-DSS including Speech-to-Text software. Additionally, the focus groups proved to be crucial at the level of utility and desires of individuals, allowing the adaptation and improvement of features already considered and the insertion of new ones. Overall, user feedback was quite positive, as reflected in the results, where users found C-DSS to be easy to learn, enjoyable and innovative. Although they considered that the workload would not increase, they showed some concern.

ANALYSIS OF THE DESIGN SOLUTIONS

The solution space is composed of all the resources and plausible alternatives to satisfy the identified problems. However, given the situation's complexity and the exhaustive list of isolated responses, we used the Menu of Ideas method shown in Table 1 to synthesise the generated ideas and allow its analysis and comparison. From this, two solution sets emerged: one focused on collaboration and proactivity activities and a second directed to perception and cognition. Finally, the incompatibility of ideas led to the elaboration of a positioning matrix (see Figure 3) to find the optimal approach. The analysis was grounded on literature review and preceding studies about navigation teamwork within the Portuguese Navy (Conceição *et al.*, 2018; Conceição, Canas and Dahlman, 2019; Cavaleiro, Gomes and Lopes, 2020).

We observed that proposal (8) assumes the most significant prominence since it helps the cognitive processes of the individuals and, while it encourages autonomy and proactiveness. On the other hand, option (3) does not

significantly promote teamwork. Conversely, option (6) promises enhanced coordination and cooperation. However, the likelihood of adding more expendable information implies a decrease in perception. In the end, the best solution could be based on an individual wearable device strengthening a shared mental map, allowing information exchange between individuals and automated agents.



Figure 3: Positioning matrix.

Requirements were prioritized with the MoSCoW classification (M- Must have, S-Should have, C-Could have, W-Will not have), and a 3-level scale was used for the development stage: preliminary (identified during the analysis); adapted (change based on UX feedback) and new (suggested by users during tests). Non-Functional requirements, associated with quality and technical condition, encompassed: usability, interaction, reliability, performance (number of users, data refresh rate), security, technical integration, laws, and norms.

Without changing existing physical arrangements and organizational structure, the C-DSS incorporates the flexible adaptations to address working arrangements and uncertainty, facilitating the variability of the joint activity. Thus, the C-DSS takes the world perception model developed by the operating bridge technological systems and merges it with the team members' perception, as they are invited to share in their perception of both direct observations and interface representation (Figure 4). This space holds the possibility to manage, adjust and redefine goals and strategies collaboratively. In the case of navigators, they usually use notebooks, with schematic plans, predefined measurements, predicted situations, procedures for teamwork coordination, goals, and strategies to control the navigation execution.

Because of the performance and personal data confidentiality, the application has login procedures. Although distinct, the four interfaces hold common elements like distance and time to wheel over point or other goals, heading, course, speed over the ground and speed through water, meteorological information, and a banner for essential information. The interfaces are coherent in design and functionality, incorporating a list of icons, i.e., functionalities relevant to their role and a situation-sensitive window, which appears without user control. Twelve individual windows have been elaborated, according to the needs of the type of user.

The navigator, ECDIS operator and chart operator, may visualize representations of the entire route plan. On the contrary, the radar operator can

only view parts of the route plan due to the radar display constraints. Additionally, the radar operator has two conflicting tasks: (1) monitor the vessel position and (2) the closest navigational hazards, requiring the selection of a 1, 5 or 3 NM display scale. On the other hand, he must appraise the forward situation to anticipate dangerous situations early, requiring the use of a 6 NM or larger scale display. Switching scales affect attention and the time required to perceive the situations (Conceição et al., 2018). Alternatively, the bridge may have two radar displays, with different scales, requiring divided attention for a single operator or additional coordination in the case of two radar operators. Finally, it also constraints the radar operator to collaboratively manage the goals out of the monitoring window, pushing him out of the teamwork.

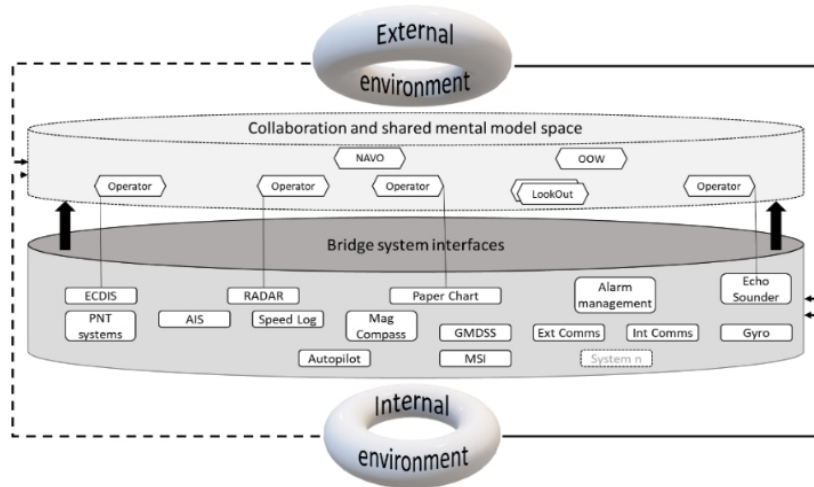


Figure 4: Representation of the application work domain.

Hence, we proposed a combined multiscale display (Figure 5), comprising a linear scale in the centre, to perceive the closest situations, and an outer exponential scale for monitoring of distant situations. A critical case is the early detection of collisions, which is detected by a track pointing to the centre (track 1, Figure 5). Despite the human ability with logarithmic scale representations, mental computation of distances is challenging. Hence, the inner scale is linear, facilitating the perceived distance as shown (Figure 5), with the two types of tracks 3 in case b), once the track gets into the linear scale, it no longer appears curved.

A speed simulator window allows the user to judge speed or ETA changes that impact over the route plan, (Figure 6(a)). Furthermore, within each length, it is possible to add new goals and appraise the best time or speed for any part of the route leg, such as replanning for launching a small boat. This process can be performed collaboratively since all may visualize the same window and interact with it.

Another tool that supports team coordination and awareness is shown in Figure 7(b), allowing the user to view the information shared by other team members and identify the time interval in which the information was updated from a colour code.

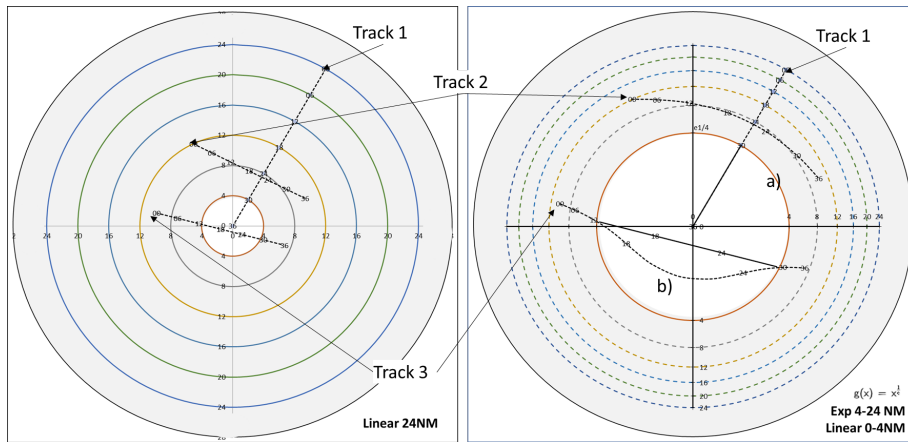


Figure 5: Combined multiscale display. Left: standard radar display with linear scale; Right: Multiscale display combining linear (0 to 4 NM) and exponential scales (4 to 24 NM).

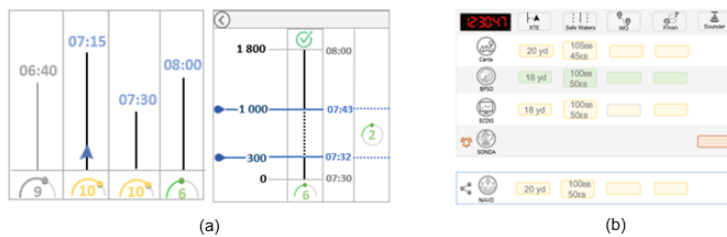


Figure 6: (a) Speed simulator. (b) Sharing information.



Figure 7: (a) Position accuracy display. (b) Visual fix coordination and bearing display.

Figure 7(a) presents a window where the user can evaluate the position obtained by the various means, with accuracy and latency indicators and view the system status. The bearing display window (see Figure 7(b), on the right) compares the planned control bearings with those taken by the lookout at any specific time (brightest colour). Based on time synchronization, it places the planning elements and observations into context, connecting the initial representation of the situation (route plan) with the system's current representation (computation of the observation and physical modelling) and the operator perception. The window presented in Figure 7(b), on the left, presents the landmarks to be used for the next fix, assigning them, and transmitting the exact update time to support the coordination and increase their

accuracy. In the example shown, the chart operator requested the starboard lookout, azimuth to the Alpha and Charlie landmark (in this order), and the Port lookout, azimuth to the Bravo marker, at 12:30:50.

DISCUSSION

At the current stage of the C-DSS development, the results indicate significant potential for the interfaces strategies, suggesting that end-users would like to have the C-DSS, considering it innovative, friendly, easy to learn and with the information they need. The main difficulties in terms of usability were related to recording data. As a possible solution, it was considered the possibility of C-DSS including Speech-to-Text software.

The navigation plan is consistent with the ones placed in the navigation system and the schemas held by each team member's notebooks. The struggle consists in simultaneously managing both technological and human agents' combined performance and contributions. Additionally, the increased uncertainty in naval operations entails continuous replanning during execution, which requires adjustments of intentions and goals. Therefore, the navigator's notebook usually has several aids and mnemonics to support the flexecution process (Klein, 2007). On the other hand, each team member carries in their notebook a different representation of the navigation plan that guides the construction of their mental model. Thus, the shared mental model is referenced to the abstract representation of the navigation plan with contextual information. The route plan sets a common ground structure to facilitate coordination and clarify communication.

There is a close relation between goals and priorities. Actions and decisions are perceived regarding their impact on the goals and fitness of the selected priorities. Bennett and Flach (2011, p. 69) also pointed to the relevance of combining the analysis of the situation with the operator's intuitions. The entire team's navigation control is supported by the route plan. The positive impact on safety due to the digital exchange of route plans between vessels and VTS has also been demonstrated (IMO, 2021).

The C-DSS tries to provide consistent and harmonized representations of the joint activity, translating the physical world knowledge into meaningful representations fitted to each user's tasks and context. Furthermore, the inclusion of feedback processes promotes interactions between team members and the technological agents, increasing the situational awareness over the system state.

As the app is designed to log all the voice communications, inputs and queries in the interface of each team member, this synchronized data is used in real-time to appraise teamwork and deliver superior situational awareness. It also provides data for further analysis of the adopted strategies and identification of competence and training need gaps, supporting the development of customized training. Consequently, this attention on everyday work variability (Work-As-Done) sets the transitional ground towards the safety II perspective and ultimately for resilient performance (Hollnagel, Wears and Braithwaite, 2015; Hollnagel, 2018).

CONCLUSION

This study contributes to the understanding of the collaborative decision-making process in navigation teams by: (1) systematising the main difficulties and challenges and, (2) presenting a desirable and viable solution. The developed prototype has four distinct complementary graphic interfaces, and oriented to the context of the user's role, based on the continuous contribution of target users, belonging to navigation teams. The contributions allowed improved understanding of the problem, idealise the solution, and improve the C-DSS, from design to insertion and adaptation of new functions.

In the validation process of the prototype, it was found that the experts would like to use the C-DSS, as they would have greater autonomy and, would be able to make an exceptional contribution. Finally, the design thinking approach provided a basis for continuous feedback from end-users, becoming a twofold benefit by triggering new ideas of possible solutions.

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