Development of a Prospective Method for Rating Surgical Task Workloads

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ABSTRACT

Surgical adverse events can have serious consequences for patients ranging from temporary injuries to death. Thereby, up to 40% of surgical adverse events are preventable and over 60% of causal factors were found to be linked to human factors. To improve surgical performance and safety, computer-assisted surgical (CAS) systems can be used to reduce excessive workloads. This paper presents a method for prospective assessment of surgical task workloads. S-TAWL, developed with the support of a senior neurosurgeon and a usability engineer, consists of three parts: surgical task decomposition, workload rating scale application, and performance shaping factors characterization. For the proposed rating scales, composed of reference operators, relative workloads were determined by 11 neurosurgeons through pairwise comparison. Afterwards, one senior neurosurgeon, not involved in method development, analysed workloads of four common surgical tasks with the proposed method S-TAWL and a reference workload assessment method Surg-TLX. Qualitatively, S-TAWL provides more detailed information about workloads with respect to human resources compared to the reference method. Quantitatively, however, the reliability of the results is still limited, as indicated by high standard deviations. Further research is needed to develop reliable and valid rating scales, compute compound workloads and identify overloads. Incorporating quantitative workload assessment in prospective human performance analysis will provide valuable information for targeted model-based design of assistance systems, supporting safe and successful surgery in the future.

Keywords: Prospective task and workload analysis, Computer-assisted surgery, Human factors

INTRODUCTION

Surgical adverse events can have serious consequences for patients ranging from temporary injuries to death [Schwendimann et al., 2018]. Up to 40% of surgical adverse events are preventable and over 60% of causal factors were found to be linked to human factors [Zegers et al., 2011]. Workloads, i.e., all external influences acting on a human, have an impact on human performance [VDI 4006 Part 1 2015]. Inadequate workloads can lead to human performance deficiencies and therefore must be avoided for safe and successful surgery [Suliburk et al., 2019].

To reduce overloads computer-assisted surgical (CAS) systems, such as cooperative robotic assistants, can be used [Schleer et al., 2021]. However, introducing technical support systems into the operating room can also increase the overall complexity of the socio-technical system, therefore increasing risks of human errors [Liu et al., 2021]. Interaction with complex systems, forces surgeons to allocate more attention on monitoring and controlling the support systems and less on the patient. Out-of-loop unfamiliarity and associated risks, like overreliance, skill deterioration, mode confusion, and reduced situational awareness can cause human errors, limiting the safety and usability of technical support systems [Endsley and Kiris 1995].

Model-based usability and human-centered risk analysis can support evidence-based design and integration of surgical assistance systems [Janß 2015] [Catchpole et al., 2022]. Various methods and models like CPM-GOMS [John and Gray 1995], Multiple Resource Theory [Wickens 2008], and mAIXuse [Janß 2015] have been proposed in literature. In military contexts, prospective workload assessment methods such as LHX or TAWL have been developed to predict task loads [Hamilton and Bierbaum 1990]. These methods involve domain experts assessing the workloads of tasks by assigning reference tasks with known workloads [Mitchell 2009]. This paper presents a method for surgical task and workload assessment (S-TAWL).

MATERIAL AND METHODS

S-TAWL is developed iteratively in accordance with the problem-solving cycle [Haberfellner et al., 2019] supported by a senior neurosurgeon and a senior usability engineer. Therefore, existing process and workload models like GOMS [Card et al., 2008], mAIXuse [Janß 2015], MRT [Wickens 2008], SPM [Neumuth 2015], TAWL [Bierbaum et al., 1989], Imprint [Mitchell 2009], and CTAWC [Knisely et al., 2021] were reviewed, adapted, and extended where necessary. The development and evaluation of S-TAWL were conducted in German and later translated into English for this publication, with the assistance of a native speaker.

S-TAWL consists of three parts: task decomposition, workload assessment using rating scales, and performance shaping factor characterization (see Figure 1). The application scope of the proposed workload assessment method is constrained to neurosurgery. Task interdependencies and resource conflicts of parallel activities are not considered and must be evaluated separately.

In a first step, the surgical process is decomposed into elementary components by a domain expert and a modelling expert. For the proposed task decomposition, terms and concepts are defined in accordance with Lalys and Janin [2014]. A *surgical process* consists of *surgical phases* that consist of a set of *surgical tasks* performed to achieve a surgical objective. A *surgical task* forms the smallest logical unit from a medical domain perspective. From a human factors domain perspective, surgical tasks are further decomposed into *surgical activities* that form a perception-cognition-action cycle [IEC 62366–1 2015]. Surgical action-type activities are also called *surgical gestures* or *surgemes* in the literature [Lin et al., 2006].

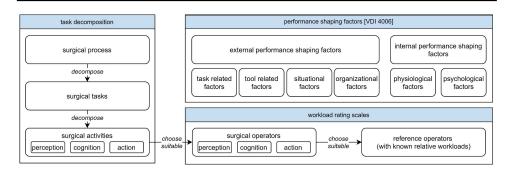


Figure 1: Structure of the proposed prospective workload assessment method S-TAWL.

In a second step, relative workload magnitudes of *surgical activities* are assessed by choosing suitable *operators*, i.e., standardized generic activities [John and Gray 1995]. Then, corresponding rating scales composed of *reference operators* with known relative workloads are applied. Thereby, various sets of operators were proposed for surgical and non-surgical process modelling in the literature [Card et al., 1980; Card 1981; Rasmussen 1983; Hamilton and Bierbaum 1990; John and Gray 1995; Hoc and Lemoine 1998; Troccaz et al., 1998; Anderson et al., 2001; Holleis et al., 2007; Estes 2021]. For the presented study a relevant subset of operators was identified and clinically meaningful reference operators were defined in workshops with clinical experts (Table 1). Further components and sources of workload are analyzed by identifying and characterizing relevant PSFs [VDI 4006 Part 1 2015]. Within the scope of this paper, a formative evaluation of the proposed rating scales is presented.

For perception and action operators, relative workloads on a 7-point scale (1- lowest workload) were determined through pairwise comparison by 11 neurosurgeons from the department of neurosurgery of the university hospital Aachen. For cognition operators, reference operators and relative workload magnitudes were defined based on an adaptation of Bloom's taxonomy [Anderson et al., 2001].

S-TAWL was then evaluated by analyzing the workloads of four common surgical tasks in posterior cervical spine fixation. This surgical procedure is an example of a very complex surgical procedure associated with high risks. The examined tasks were: (1) navigated drill guide alignment, (2) non-navigated drill guide alignment, (3) canulated pedicle screw placement, and (4) noncanulated pedicle screw placement. First, these tasks were decomposed into surgical activities with the support of a senior neurosurgeon. Subsequently, a different senior neurosurgeon from the university hospital Aachen, who had conducted approximately 50 cervical spine fixations, assessed the workloads. For each activity, the surgeon was asked to identify suitable reference operators that they believed to be most similar in terms of workload. The reference operators were presented without numeric workload values and were not ordered on a rating scale. This approach ensured that the surgeon assigned reference operators based solely on relative comparisons, rather than absolute workload assessments. Cognitive activities were not predetermined; instead, the surgeon was asked to select all cognitive operators they deemed necessary to complete each surgical task under analysis. Following the workload assessment, the surgeon was asked to indicate which surgical activity presented the greatest challenge in assigning a reference operator. Surg-TLX [Wilson et al., 2011], an adaptation of NASA-TLX, was used as a reference method to assess workloads. The participating surgeon was not involved in the development of S-TAWL.

RESULTS

For perception and action operators, the identified mean relative workloads and standard deviations are shown in Table 1. Reference operator workload estimates show that the proposed rating scales are not equidistant. Due to high standard deviations (up to ± 2 points) some rating scales are ambiguous, such as for the operator *primarily coordinative actions*. For the two operators *visual search* and *haptic interpretation*, two reference operators within one rating scale were determined to have the same workload. Furthermore, no rating scale covers the entire 7-point range. The smallest rating scale span is 2.9 points (*visual search*, *primary physical actions*) and largest rating scale span is 4.5 points (*visual identification*).

Workloads assessed with the proposed method S-TAWL and the reference method Surg-TLX are shown in Table 2. For drill guide alignment, reported total workload with Surg-TLX (0-lowest, 100-highest) was similar with (32) and without (33) navigation. Raw ratings were highest for mental demands and task complexity and lowest for physical demands. For pedicle screw placement, total weighted workloads are lower for placing canulated screws (22) than for placing non-canulated screws (35). Raw ratings indicated that for canulated screw placement physical demands were highest, while for non-canulated screw placement mental demands were highest, while for non-canulated screw placement mental demands were highest. Weights determined through pairwise comparison show that mental demands (w = 5) are more important than any other factor, while physical demands are not relevant at all (w = 0). Therefore, despite being rated higher for pedicle screw placement compared to drill guide alignment, physical demands do not contribute at all to the total weighted workload.

With S-TAWL main differences for assessed workloads were related to perception type activities. S-TAWL task decomposition suggests that drill guide alignment only includes visual perception, while pedicle screw placement includes visual and haptic perception. For navigated and non-navigated drill guide alignment, workloads for monitoring and verifying the alignment using anatomical landmarks were rated highest. Alignment verification in X-ray imaging was rated as a high-workload *visual identification* task, while monitoring alignment on a navigation display was rated as a low-workload *visual search* task. For pedicle screw placement, workloads for visual checks of the screw alignment are rated lower for canulated screws (2.1) than for non-canulated screws (4.4). Visual screw depth monitoring is rated as the lowest *visual search* task (2.5) for canulated screws. For haptic alignment control, different reference operators were assigned, however both having the

activity type					Cognition					
operator	Remember retrieve relevant knowledge from long- term memory	rel. workload	Understand construct meaning	rel. workload	Analyse break material into its constituent parts and determine interrelations	rel. workload	Evaluate make judgements based on criteria and standards	rel. workload	Cre a te put elements together to form a coherent or functional whole	rel. workload
stote	recognising locating knowledge in long-term memory that is consistent with presented material	-	classifying determining that something belongs to a category	7	differentiating distinguishing relevant from irrelevant parts or impor- parts or mortion tarts of mesented material	3.5	checking detecting inconsistencies of fallacies within a process	4.5	generating coming up with alternative hypothesis based on criteria	ø
sience opers	re calling retrieving relevant knowledge from long- term memory	1.5	inferring drawing a logical conclusion from presented information	2.5	organized material organized by the second s	4	decision - making (simple) choosing between multiple options where reasoning is clear or errors have insignificant consequences	a	pla nning devising a procedure for accomplishing a task	6.5
əfər			comparing detecting correspondences between two ideas, objects, and the like	ю			decision-making (difficult) choosing between multiple options where reasoning is unclear or errors have significant consequences	5.5	producing inventing a new solution	7
activity type				Perception	ption					
operator	Visual Search find elements, e.g. in the surgical field, on the navigation screen or in a CT image	rel. workload	Visual Identification recognize elements, e.g. in the surgical field, on the navigation screen or in a CT image	rel. workload	Haptic Discrimination recognise differences between elements based on haptic information, e.g. tissue stiffness	rel. workload		rel. workload		
	localise cranial sutures on an exposed skull	2.1 (±1.2)	detect a meningioma (<2 cm diameter)	2.5 (±1.3)	manual palpation of carotid artery	1 (±0)	estimate the necessary cutting force and depth for cutting skin with a	2.1 (±1)		
perators	localise an arterial bleeding	3.6 (±1.5)	identify a non-infiltrating, displacing tumour with a clear boundary	2.6 (±1.5)	recognise the difference between driling in cancellous and cortical	4.3 (±1.2)	scaper estimate the necessary cutting force and depth for cutting muscle with a	3.2 (±1.3)		
o eoner	localise a venous bleeding	4.4 (±1.1)	detect adhesive and slightly infiltrating metastases	4.3 (±0.9)	palpation with a hook of a stenosis in the neuroforamen/spinal canal	5.2 (±1)	estimate the necessary contact force when sawing bone	4.5 (±1.2)		
əfən	find structures in fat tissue, e.g. peripheral nerves find a carotid-T aneurysm (intracranial)	5 (±1) (±2)	identify an infiltrative growing brain tumour (degenerated brain cells)	6.6 (±1)	manual palpation of jugular vein	5.5 (±1.9)	estimate the appropriate feed rate when drilling in bone estimate the necessary force for milling bone	5.1 (±1) 5.1		
activity type				Action	ion					
operator	Primarily Physical Actions simple movements that do not require practice and involve physical exertion	rel. workload	Primarily Coordinative Actions complex movements that require practice and fine motor skills	ce and fin	e motor skills			rel. workload		
	remove bone screw reposition patient hammerin implant (knee, hio)	2.8 (±1.7) 3.4 (±1.6) 4.1(±1.5)	2.8 (±17) probe artificial landmarks with pointer (e.g. during registration) 3.4 (±16) probe anatomical landmarks with pointer (e.g. during registration) 4.1(±15) hoosition an instrument at a desired point with desired orientation (i	g. during ar (e.g. du t with desi	2.8 (±17) probe antificial landmarks with ponter (e.g. during registration) 3.4 t.15) probe antaromical andmarks with ponter (e.g. during registration) 4.1 t.15) prosto antaroment at a desired control with Gesined to indentiation (e.g. find start cossion for diffino)	dillina)		2.1(±0.8) 2.2 (±0.9) 4.4 (+0.9)		
referei Breqo	hold a soft-tissue retractor (spine, knee)		I follow a trajectory with an instrument (e.g. drilling along a trajectory, milling path to rer remove material in a confined plane (e.g. sawing task TKA, milling task laminectomy)	g. drilling J. sawing	5.7 (±16) follow a trajectory with an instrument (e.g. drilling along a trajectory, milling path to remove bone) remove material in a confined plane (e.g. sawing task TKA, milling task laminectorny)	oone)		4.7 (±1.2) 5.1(±0.9)		
			remove material in a contined volume (e.g. remove tumour/cystic neoplasm)	e.g. remov	e tumour/cystic neoplasm)			5.5 (±0.9)		

Table 1. Rating scales and relative workloads for cognition-type surgical operators adapted from [Anderson et al., 2001]. Rating scales for perception-

				posterior cervical (C7) spine	e fixation	spine fixation - pedicle screw placement					Surra-TI Y	S-TAWL
surgical task	surgical activity	activity type	operator	reference operator	surgical task	surgical activity	activity type	operator	reference operator	100 augusted drill guide alignment	Jourg-1 LA Inon-mavigated drill guide alignment pravinstad drill guide alignment	non-navigated drill guide alignment
	check pedicle and drill guide position within the surgical site in relation to anatomical	per (vis	n visual search	find structures in fat tissue, e.g. peripheral nerves (5)		check pedicle and drill guide percepti position on the navigation screen (visual)	u	visual search	localise cranial sutures on an exposed skull (2.1)	8 200 200		9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9
	verification of the pedicle position in the lateral x-ray image (in one plane).	ge (visual)	perception visual ident- (visual) ification	detect adhesive and slightly infiltrating metastases (4.3)		(supplementary) verification of drill guide alignment using anatomical landmarks	perception (visual)	visual search	find structures in fat tissue, e.g. peripheral nerves (5)	sk load ind 8 8 8 8		97 22 22 22 22 5 22 5 5 5
e drill guide : perfor	cognitive activities necessary to perform the surgical task	cognition	various	recognising (1), inferring (2.5), comparing (3), differentiating (3.5), decision-making (difficult) (5.5), planning (6.5)	drill guide ali	cognitive activities necessary to perform the surgical task	cognition	various	recognising (1), recalling (1.5), inferring (2.5), checking (4.5), decision-making (simple) (5), planning (6.5)		4 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	. 0
-	oold drill guide in position	action	primary physical action	hold a soft-tissue retractor (spine, knee) (5.7)		nold drill guide in position	action	primary physical action	hold a soft-tissue retractor (spine, knee) (5.7)	- × ?	w=4 w=1 w=1	STORE STORE STORE STORE STORE
	align drill guide	action	primary coordinative action	follow a trajectory with an instrument (e.g. drilling along a trajectory, milling path to remove bone) (4.7)		align drill guide	action	primary coordinative action	position an instrument at a desired point with desired orientation (e.g. find start position for drilling) (4.4)	Merinal Derritoria Derritoria	and the second state	Visual Manufacture Interaction Providence of the Open Visual Visuality Providence of the Open Visuality of the
check surgic	check screw position within the surgical site	perception (visual)		visual search localise a venous bleeding (4.4)	0 0	check screw position within the surgical site	perception (visual)	visual search	localise cranial sutures on an exposed skull (2.1)	Surg	Surg-TLX	S-TAWL
	monitor screw depth	perceptior (visual)	n visual search	perception visual search exposed skull (2.1) (visual)	~	monitor screw depth	perception (visual)	perception visual ident- (visual) ification	detect a meningioma (<2 cm diameter) (2.5)		non-canulated screw insertion canulated screw insertion	Canulated screw insertion
	position and alignment control using haptic feedback during screw insertion	perceptior (haptic)	perception haptic inter- (haptic) pretation			position and alignment control using haptic feedback during screw insertion by sliding the K- wire back and forth	perception (haptic)	perception haptic inter- (haptic) pretation	estimate the necessary force for milling bone (5.1)	80 - 80	ی ک ک ک ک ک ک ک	6.5 6.7 6.7 6.7 6.7 6.7 6.7 6.7 6.7 6.7 6.7
nated pedicle sci	cognitive activities necessary to perform the surgical task	cognition	various	recognising (1), recalling (1.5), inferring (2.5), comparing (3), differentiating (3.5), checking (4), decision-making (difficult) (5.5), planning (6.5)	ted pedicle screv	cognitive activities necessary to perform the surgical task	cognition	various	recognising (1), inferring (2.5), checking (4.5), decision-making (simple) (5), planning (6.5)	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		52 (Josef reference) 52 54 54 54 54 54 54 54 54 54 54
	screw insertion	action	primary physical action	hold a soft-tissue retractor (spine, knee) (5.7)	•,	screw insertion	action	primary physical action	hold a soft-tissue retractor (spine, knee) (5.7)	,	Lanv Saw bank	
maint	maintain screw alignment	action	primary coordinative action	follow a trajectory with an instrument (e.g. drilling along a trajectory, milling path to remove bone) (4.7)		maintain screw alignment	action	primary coordinative action	follow a trajectory with an instrument (e.g. drilling along a trajectory, milling path to remove bone) (4.7)	Wartun Dernamon Dernamon Wartun Dernamon Dernamon Profession Dernamon Frank	And the stream stream of the stream	Varia Son Marcumine and Annual Annual Varian Variante Variante Variante Annual Annual Variante Variante Variante Variante Variante Variante Variante Variante



same identified workload (5.1). Regarding cognition type activities, all four tasks require recalling (1), inferring (2.5) and planning (6.5). For navigated drill guide alignment and canulated pedicle screw insertion decision-making (simple) (4.5) is chosen, while for non-navigated drill guide alignment and non-canulated pedicle screw placement decision-making (difficult) (5.5) is chosen. For non-canulated screw placement 8 reference operators are chosen, while for canulated screw placement only 5 are chosen. Regarding action type activities, primarily physical actions were rated high (5.7), while workloads for primarily coordinative actions were rated medium (4.4-4.7) for all four tasks. In applying the method, the surgeon reported that they struggled most with assigning cognitive reference operators.

DISCUSSION

As human factors are a significant contributor to preventable adverse events in surgery, accurate and reliable workload assessment is key for safe and successful surgery. However, surgical workload assessment is challenging due to task variability and a large number of interdependent influencing factors. While performance shaping factors indicate sources of workload, assessment of compound workload magnitudes of individual activities is challenging [Heard et al., 2018]. In this paper a prospective workload assessment method based on rating scales composed of reference tasks was proposed. The limited scope of the formative evaluation study with only one participating surgeon does not allow for final conclusions about reliability or validity of the proposed method. However, some general conclusions about the design of the method can be drawn for future considerations.

Comparing the assessed workloads using Surg-TLX and S-TAWL is challenging due to differences in workload components and the current lack of a method to compute compound workloads with S-TAWL. Nonetheless, some results show similar tendencies: Both methods rate non-canulated pedicle screw placement to be more demanding than canulated pedicle screw placement. With Surg-TLX ratings are higher for complexity and mental demands, while S-TAWL shows increased workloads for visual perception activities. However, there are also some disparities: Surg-TLX reports higher raw ratings for physical demands in pedicle screw placement compared to drill guide alignment, while S-TAWL rates physical demands similarly high for both tasks. However, for Surg-TLX, differences in raw ratings do not affect compound workloads because the determined weighting factor is 0.

By enabling a more detailed assessment of workloads related to perceptual, cognitive, and motor demands S-TAWL facilitates the identification of resource conflicts and excessive workloads when combined with existing model-based risk analysis methods [Dell'Anna-Pudlik 2022]. However, computation of compound workloads with S-TAWL remains an open research question. To compare workloads across multiple operators weighting factors may be added [Virtanen et al., 2022]. Furthermore, operator interferences could be considered using a conflict-matrix as proposed by Wickens [2002]. Finally, researching limits for acceptable compound workloads with respect to human performance capacity is crucial to determining excessive workloads.

When using S-TAWL's rating scales, which are composed of reference operators, workloads are assessed through relative comparison. Studies indicate that relative rating methods, such as paired comparisons, appear to have greater validity and reliability than absolute rating scales, such as the NASA TLX [Vidulich and Tsang 1987]. However, the presented evaluation study showed that adaptation of the proposed rating scales is necessary. The proposed rating scales for perception and action operators exhibit limited reliability as indicated by high standard deviations in the determined relative workloads. Measurement sensitivity is affected by scale non-linearity, a limited scale span, and varying numbers of scale steps. Additionally, there are potential limitations in the measurement range due to scale attenuation effects. Regarding cognition operators, further research is necessary to validate the proposed linear rating scale, which is based on Bloom's taxonomy, originally developed to describe student learning.

For the assignment of reference operators to surgical activities, the optimal choice of reference operators is an open research question. Highly specific reference operators from the user's field of expertise may improve the assignability, while more general operators, such as those form a surgical training curriculum [Acosta et al., 2018], may increase the method's application scope. During the study, the participating neurosurgeon reported having the most difficulty with the assigning cognitive operators. This may be either because cognitive activities were not further specified or because cognitive reference operators were selected it was unclear whether the assigned reference operators referred to separate cognitive activities. Due to the hierarchical structure of Bloom's taxonomy higher-level reference operators include lower-level operators.

CONCLUSION

Human factors play a significant role in preventable adverse events, highlighting the importance of accurate and reliable workload assessment to proactively identify risks arising from excessive workloads. The proposed task decomposition and operator definition in S-TAWL offer valuable insights into the workloads associated with perceptual, cognitive, and motor demands of surgical tasks. However, determining compound workloads still presents a challenge. Future research is essential to incorporate task interrelationships, resource utilization, and all relevant performance shaping factors in the evaluation of surgical task workloads. Extending existing model-based risk analysis methods with an accurate and comprehensive workload analysis can support evidence-based design of assistance systems and promote safe and successful surgery in the future.

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