

Validation of Wearable Biosignal Sensor-Based Estimation of the Physiological Strain Index Using Gaussian Process Regression

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ABSTRACT

At physiologically intensive work or during acute exercises, early alert functions are highly required to prevent physiological damage to human health. Wearable sensor-based monitoring of vital parameters can provide real-time measures for the quantification of a worker's individual psychophysiological and thermal strain to define risk levels for appropriate decision support. One of the most well-recognized indices suitable for use in the workplace so far is the Physiological Strain Index (PSI; Moran et al., 1998) based on sensor data about (i) the core body temperature (CBT) as well as (ii) the heart rate (HR). Until recently, the ground truth information about CBT was particularly measured by cumbersome swallowing expensive gastrointestinal temperature pills. A more comfortable strategy is to attach bioelectrical temperature sensors to the human skin and from these data provide an estimate about the CBT. Dolson et al. (2022) provided a systematic review on distinct algorithms to predict the core body temperature using wearable technology. Most of these algorithms deployed Kalman filters for the prediction. Only a few algorithms incorporated individual and environmental data into their core body temperature prediction, despite the known impact of individual health and situational and environmental factors on the CBT. The presented Machine Learning (ML) framework provides a comparison between a large set of Artificial Intelligence (AI) methods. The Gaussian Process Regression method (GPR; Rasmussen and Williams, 2006) has determined the minimum root mean square error (RMSE) on data from a highly challenging exercise profile applied by a wildland firefighter group. The results are highly competitive with the methods reported in Dolson et al. (2022).

Keywords: Physiological strain index, Wearable biosignal sensors, Machine learning

INTRODUCTION

The monitoring of vital parameters can provide real-time measures to determine the worker's individual physiological and thermal strain level. This measure has been suggested to provide risk levels for decision support for a personalized protection from either heat or cold-related health damage. Recent technological advancements have led to rapid growth in the

development of wearable physiological monitors and subsequent research on the utility of these systems. One of the most well-recognized indices suitable for use in the workplace so far is the PSI (Moran et al., 1998) that was developed to reduce incidences of heat-related health damage at an individual level in the military (Moran et al., 1998).



Figure 1: Wildland firefighters at the test site (Šapjane, center of firefighters Rijeka; 2021). The load profile consisted of 2 rounds each including four firefighter characteristic activities (left to right): marching uphill/downhill with 20 kg backpack (HC20), fire swatter exercise, hosing, and marching again, each with a duration of 5 minutes. Between the 2 rounds there was a break of 10 minutes.

The modified physiological heat strain index (PSI*; Buller et al., 2008, 2015; Seeberg et al., 2013) is usually determined from heart rate and skin temperature sensor data. PSI* is often preferred since it approximates the CBT that otherwise needs to be measured by gastrointestinal temperature pills. The precision in the measurement of the CBT being derived from the skin temperature sensor data using a mapping factor fundamentally determines the precision of the estimated PSI. The error between the two quantities PSI and PSI* was described to be tolerable (Buller et al., 2018) in practice if it lies within ca. 2 standard deviations of the RMSE. However, linear, or nonlinear regression can be applied to estimate CBT from measured skin temperature and can further reduce the error. The complexity of the human thermoregulatory models suggests that the responses of CBT and physiological measures are part of a dynamical system (Buller et al., 2018). Exploiting knowledge of physiological relationships between variables has led to successful estimation of hidden variables. This type of problem can be represented as, for example, a Hidden Markov Model (discrete) or a Kalman filter (continuous; Buller et al., 2013; Buller et al., 2018). Some companies provide information about the performance figures of estimating CBT from wearable sensors that measure skin temperature data, but first optimistic data could not be reproduced so far (Düking et al., 2018; Verdel et al., 2021).

Our work intends to close therefore a gap by computing, reporting and understanding the potential to estimate CBT and PSI from wearable sensors and (non-)linear regression methods. For that reason, we recorded real biosignal data from a training with 12 first responders (Šapjane, Center of Firefighters Rijeka, Croatia; June 2021) with a load profile being characteristic for wildland firefighters (Figure 1). We used gold standard biosignal sensors for heart rate and skin temperature (measured laterally on the chest)

information, as well as gastrointestinal temperature pills to get the CBT ground truth. Then we set up an ML-based framework to provide a comparison between a large set of 26 different, mostly AI-based, methods including neural network approaches. In a next step, we rated all methods using 5-fold cross-validation and found that the Gaussian Process Regression (GPR) provided the minimum RMSE of 0.279 °Celsius compared to our measured ground truth core body temperature. Finally, the GPR-based method was used to estimate PSI and attained absolute error values of $M = 0.151$, $SD = 0.185$ (RMSE $M = 0.238$) related to the ground truth PSI value, which is in contrary to the linear fitted model that achieved absolute error values of $M = 1.026$, $SD = 0.640$ (RMSE: $M = 1.209$) points. This finally represents a substantial improvement for a decision support system that should provide the most appropriate warnings and alerts in the case of high risk of physiological strain.

RELATED WORK

The complexity of the human thermoregulatory models suggests that the responses of CBT and other physiological measures are part of a dynamical system (Buller et al., 2018). With the use of current physiological monitoring techniques, certain variables, such as, heart rate and skin temperature, can be readily observed, whereas others, the CBT, in particular, can only be readily observed directly in a laboratory setting. Exploiting knowledge of physiological relationships between variables has led to successful estimation of hidden variables. This type of problem can be represented as a Hidden Markov Model (discrete) or as a Kalman filter (continuous; Buller et al., 2013; Buller et al., 2018). Both models accommodate the complex time-based relationships of the human thermoregulatory system, and both take the form of recursive algorithms based on Bayesian inference, estimating the state of the system and repeatedly updating that state from the next observation. A Kalman filter is used when the data can be modeled as continuous linear Gaussian distributions. A Hidden Markov Model is used when the data are modeled as discrete states, each with its own likelihood of occurring. Belval (2016) presented several different Machine Learning methods that can be utilized in the development of prediction models for internal body temperature during exercise in the heat. For a regression model, he found a multivariate adaptive regression splines model performed best. Dolson et al. (2022) provided a systematic review and identified 20 studies representing a total of 25 distinct algorithms to predict the core body temperature using wearable technology. Most of these algorithms provided Kalman filters for the prediction. Only few algorithms incorporated individual and environmental data into their core body temperature prediction, despite the known impact of the individual health status as well as situational and environmental factors on the CBT. The RMSE error was found to be on average (wearable on chest, 322 subjects) $0.29\text{ °C} \pm 0.14\text{ °C}$, a single, best one (wearable at the wrist, 15 subjects) reported an RMSE of 0.13 °Celsius (Nazarian et al., 2021). Some companies provide information about the performance figures of estimating CBT from wearable skin temperature sensors. For example, the CORE sensor

(greenTEG AG, Rümlang, Switzerland) has been made commercially available. It computes CBT based on heat flux and published an error threshold of 0.3 °Celsius. Some researchers could not yet reproduce this in documented trials (Düking et al., 2018; Verdel et al., 2021). Daanen et al., (2023) provides an overview with detailed insight on the performance of relevant heat flux-based temperature sensors.

In our work, we present an ML-based framework with a comparison between a large set of AI methods, including neural network approaches, and finally determined the minimum RMSE of 0.279 °Celsius to be found by the GPR method.

PHYSIOLOGICAL STRAIN INDEX AND RISK LEVELS

The proposal for the **physiological strain modelling**, in line with Buller et al. (2008), consists of using **PSI** (Moran et al., 1998) using the CBT as a starting point in the physiological strain assessment. PSI^* uses the **raw skin temperature** instead of the CBT by

$$PSI^* = 5 * \frac{(T - T_0)}{(T_{max} - T_0)} + 5 * \frac{(HR - HR_0)}{(HR_{max} - HR_0)},$$

where HR_0 and T_0 denote heart rate (HR) and skin temperature (T) at baseline before exercise; T_{max} is the critical skin temperature established at 39.5 °C; and HR_{max} is considered the maximum heart rate (bpm) pre-determined during a performance test or calculated based on the subject's age according to Tanaka et al. (2001).

We assigned classification labels for **alerting** of a concrete **risk** for physiological collapse upon $PSI^* \geq 7.5$ (“at-risk”), and $PSI^* < 7.5$ “not-at-risk”. However, taking experimental data into concern (Carballo-Leyenda et al., 2023), $PSI^* \geq 6$ appeared to be a good threshold for assessing physiological risk. Once an “at risk” classification has been made, additional physiological parameters could act as a second step validation of the physiological state of the first responder (i.e. heart rate thresholds, skin temperature thresholds). Yokota et al. (2005) established that, when using heart rate and skin temperature to assess physiological strain risk, a reasonable classification boundary would deal effectively with three conditions:

1. high heart rate and high skin temperature indicate “at-risk”,
2. high heart rate and lower skin temperature indicate “not-at-risk”,
3. high skin temperature, regardless of heart rate, indicates “at-risk” unless contextual information suggests otherwise.

Keeping in mind that the study of Yokota et al. (2005) focused on heat strain, it should be considered to add another boundary to account for exposure to cold environment that would be the expected scenario for Mountain Rescuers. For this reason, the boundary condition for cold exposure would be:

4. very low skin temperature, regardless of heart rate, indicates “at-risk”.

RATIONALE OF METHODOLOGY

The gold standard method for measuring the CBT requires the test person swallowing a temperature measuring capsule. The pills must be swallowed at least 6–8 hours prior to testing to minimize the confounding influence of food or fluid on the pill measurements (Wilkinson et al., 2008). The quality of the measurement depends on where the pill resides in the body during the measurements and the method is very cost intensive. In contrast, the PSI* indicator is based on the skin temperature instead of the CBT since the skin temperature values can be measured much more easily at the chest of a subject.

We firstly developed a linear model that best fits PSI* to PSI (Carballo-Leyenda et al., 2023). This model is a good starting point, but still approximates PSI with relatively large deviations. To increase the accuracy of the PSI estimation model, we applied several nonlinear approximation methods and also extended the input parameter set: skin temperature [°C], heart rate [bpm], age [years], weight [kg] and height [m]. The output variable represents the objective of the estimation, the core body temperature [°C]. It's associated ground truth for the supervised machine learning was the capsule-based gold standard CBT measurement.

The category sex was currently also included in the models but only for possible future use. At present, the parameter has no influence, since only training data from male firefighters were available for training the models.

GAUSSIAN PROCESS REGRESSION AND EXPLAINABLE AI

Gaussian Processes (GP) are a nonparametric supervised learning method used to solve regression and probabilistic classification problems. There are many advantages of Gaussian Processes. First, the prediction interpolates the observations (at least for regular kernels) and it is probabilistic (Gaussian) so that one can compute empirical confidence intervals and decide based on those if one should refit the prediction in some region of interest. GP are also very versatile in terms of the kernels that can be used: common kernels are provided, but also custom kernels may be specified. Gaussian processes have also disadvantages. The implementation is not sparse, i.e., they use the whole samples/features information to perform the prediction. Furthermore, they lose efficiency in high dimensional spaces – namely when the number of features exceeds a few dozens.

GPR implements Gaussian Processes for regression purposes. For this, the prior of the GP needs to be specified and combined with the likelihood function that is based on training samples. It enables a probabilistic approach to prediction by providing the mean and standard deviation as output when predicting¹. A GPR model can make predictions incorporating prior knowledge (kernels) and provide uncertainty measures over predictions. Figure 2 depicts a schematic sketch of the concept of GPR. Data points (red) are distributed in n-dimensional data space. The GP model X^* (blue) describes then a probability distribution over possible functions that fit a set of points. GPR is a fundamental model used in machine learning. Owing to its accurate prediction with uncertainty and versatility in handling various data structures via

¹https://scikit-learn.org/stable/modules/gaussian_process.html

kernels, GPR has been successfully used in various applications. With GPR, however, it is not possible to interpret how the features of an input contribute to its prediction.

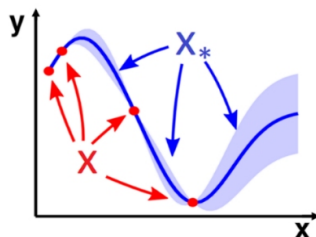


Figure 2: Schematic sketch of the concept of GPR. Data points (red) are distributed in n -dimensional data space and estimated to represent the final GP model X^* (blue).

Yoshikawa and Iwata (2020) proposed GPR within a framework of **eXplainable AI** (XAI; Mueller et al., 2019), i.e., with local explanation. It reveals the feature contributions to the prediction of each sample, while maintaining the predictive performance of GPR. Experimental results in Yoshikawa and Iwata (2020) verified that the proposed model can achieve predictive performance comparable to those of GPR and superior to that of existing interpretable models, and can achieve higher interpretability, both quantitatively and qualitatively.

EXPERIMENTAL RESULTS

Study protocol. Wildland firefighters ($N = 13$; RJ01 to RJ13) performed a pre-planned exercise field test at the test site Šapjane (Center of Firefighters Rijeka; June 2021) in Croatia. The exercise field test was arranged in 2 rounds and intended to mimic the activities and the physiological strain of wildland firefighters (Rodríguez-Marroyo et al., 2012). Each round was divided into 4 sections with characteristic activities (see Figure 1): marching uphill and downhill with a 20 kg backpack (HC20), hitting the fire swatter, hosing, and marching uphill/downhill (HC20) again, each with a duration of 5 minutes. After completion the first round and having a break of 10 minutes, the second round was carried out. On average, ambient temperature and relative humidity were 32.2 ± 2.1 °C and 41.7 ± 5.2 (%). The duration of the overall test session (i.e., including the psychological pretest and post-test assessment) was 96.5 ± 42.8 min. Considering the field test protocol itself, the duration was 54.9 ± 2.7 min for those who completed the two rounds of the test. For those who performed only a shortened version of the field test (i.e., RJ07, RJ08 and RJ09), the duration was 26.0 ± 4.3 min. As intended, the participants experienced high to very high levels of cardiovascular and thermoregulatory strain. The mean gastrointestinal temperature (T_{gi}) was $M \geq 38$ °C, which is considered the threshold of hyperthermia (e.g., mild hyperthermia) in occupational settings (NIOSH, 2016). In the current study, chest skin temperatures ranged from 34.0 to 37.7 °C (i.e., moderate to high skin temperature), being the upper value of the skin temperature range close to maximal skin blood flow perfusion level (Nybo et al., 2014). In line with the

behavior of T_{gi} , the average HR values assume a moderate effort intensity of around 78% of each participant maximal heart rate (i.e., HR_{max}).

Data collection. We used 12 out of the 13 available data sets from the wildland firefighters that were recorded during the field tests in Rijeka. One dataset (subject RJ11) was discarded due to many artefacts in the heart rate (HR) signal. In addition, from the available datasets, only the time intervals covered by all necessary bio-signals were used. In some cases, artefacts or non-valid intervals of values were also excluded from the ML training. For the training of the non-linear model, we used gold standard data recorded by the Universidad de León in Croatia. After data cleaning, 971 of the original 1736 data sample vectors of the 12 subjects remained to train the non-linear models.

Results of regression estimation. We trained and validated several linear and non-linear models on the Rijeka data. These models included Linear Regressions, Multilayer Perceptron Networks, Gaussian Process Regression (Rasmussen and Williams, 2006), Support Vector Regression, Kernel Regressions and Regression Trees. For the training and validation, we resampled the data on a basis of 1-minute time intervals and applied 5-fold cross-validation. We used the MATLAB² implementation of all models that are mentioned in Table 1 and found the minimum RMSE by the GPR method. The GPR model is based on a nonparametric kernel-based probabilistic attempt; the best performing kernel on the clean data was the exponential one ($\text{SigmaL} = 2.404$, $\text{SigmaF} = 0.724$). We used a constant basis function, an “exact” fitting method and a “random” active set method. The remaining model parameters are $\text{Beta} = 38.017$, $\text{Sigma} = 0.195$ and $\text{LogLikelihood} = -242.504$. The validation using 5-fold cross-validation on the data resulted in $\text{RMSE} = 0.279$ °C and a mean squared error (MSE) of 0.078 °C (see Table 1). Note that we learned the core body temperature and used the predicted value for the subsequent PSI calculation.

Table 1. Performance of various machine learning-based linear and nonlinear function approximations for the estimation of CBT, characterized by RMSE based validation error. GPR is marked yellow and performed best.

Model Type (Kernel/Method)	RMSE (Validation)	MSE (Validation)	RSquared (Validation)	MAE (Validation)
Gauss. Process Regr. (exp.)	0.279	0.078	0.812	0.181
Gauss. Process Regr. (rat. Quadric)	0.280	0.079	0.811	0.182
Gauss. Process Regr. (matern 5/2)	0.285	0.081	0.805	0.189
Gauss. Process Regr. (squared exp.)	0.296	0.088	0.789	0.201
SVM (RBF fine)	0.297	0.088	0.788	0.186
Ensemble (bagged trees)	0.310	0.096	0.769	0.222
Tree (fine tree)	0.331	0.110	0.735	0.211
Tree (medium tree)	0.332	0.110	0.735	0.227
SVM (cubic)	0.352	0.124	0.701	0.247
SVM (RBF medium)	0.362	0.131	0.685	0.249
Tree (coarse tree)	0.365	0.133	0.679	0.276
Neural Network (tri 10-10-10 ReLU)	0.377	0.142	0.658	0.274
Neural Network (bi 10-10 ReLU)	0.380	0.144	0.652	0.280
Neural Network (WNN ReLU)	0.391	0.153	0.632	0.291
Least Squares Kernel Regression	0.394	0.155	0.626	0.297
Neural Network (MNN ReLU)	0.410	0.168	0.595	0.307
Kernel Regression (SVM)	0.412	0.170	0.591	0.283
SVM (quadric)	0.428	0.183	0.559	0.303
Linear Regression	0.433	0.188	0.548	0.322
Stepwise Linear Regression	0.436	0.190	0.542	0.324
Neural Network (NNN ReLU)	0.444	0.197	0.525	0.343
SVM (RBF coarse)	0.455	0.207	0.501	0.345
Linear Regression	0.488	0.238	0.427	0.394
Linear Regression	0.489	0.239	0.425	0.394
SVM (linear)	0.496	0.246	0.408	0.393
Ensemble (boosted trees)	1.655	2.739	-5.596	1.622

²MATLAB © Version 9.13.0.2126072 (R2022b) Update 3 and MATLAB’s Statistics and Machine Learning Toolbox Version 12.4 (R2022b).

The course of data presented in Figure 3a provides insight into the difference between the gold standard CBT measure (in blue) – taken as ground truth – and the predicted CBT (in red). Figure 3b and Figure 3c show the scatter plots of PSI and fitted/estimated PSI comparing the solution between the linear model (left) with the GPR model (right) on artefact-adjusted data when using fixed, pre-determined min/max heart rate and skin temperature values. The $x=y$ diagonal represents a theoretically perfect match. Table 2 provides the results for a performance comparison between PSI and estimated PSI using fixed min/max values for the input parameters heart rate and skin temperature. The first line shows results for taking the raw skin temperature for the PSI*, the second line for estimating PSI by a linear model and the third line for estimating PSI by GPR model on the whole (left) and valid data (right).

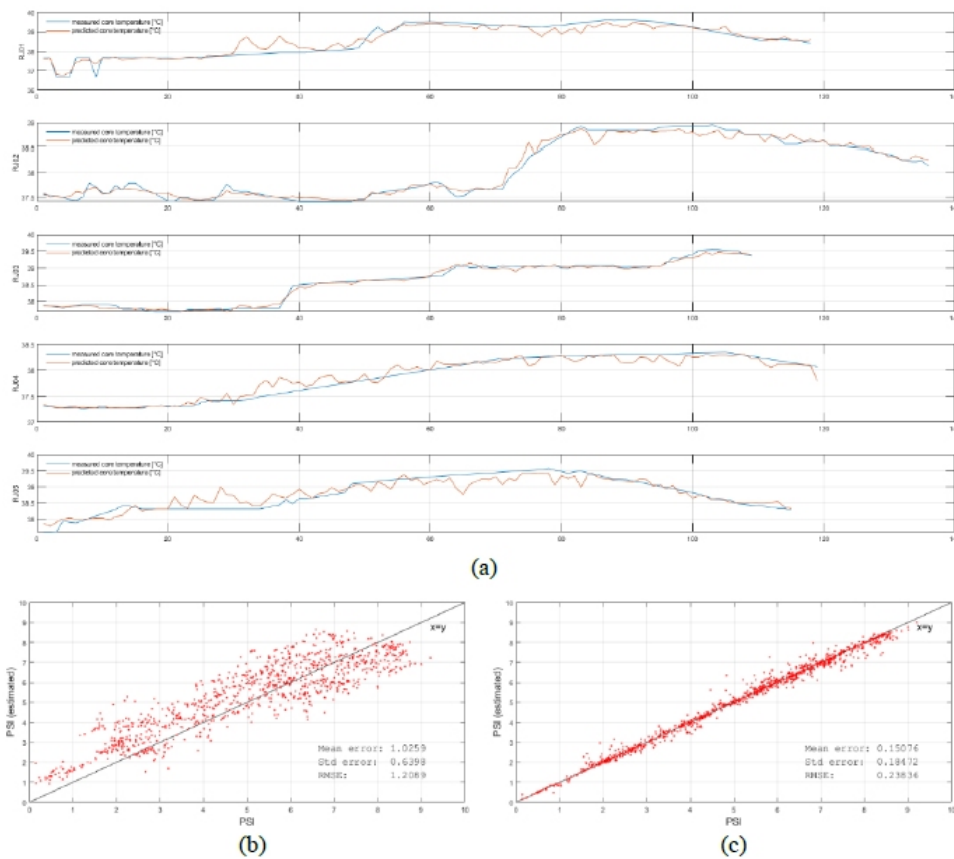


Figure 3: Performance of predicting CBT using GPR. (a) Course of data showing the difference between the gold standard CBT measure (in blue) - taken as ground truth - and the predicted CBT (in red). (b, c) Scatter plots of PSI and fitted/estimated PSI* comparing linear model (left) with GPR model (right) on artefact-adjusted data. The error measures denote absolute errors (M, SD) as well as RMSE.

Table 2. Performance comparison in terms of absolute errors (M, SD) as well as RMSE between PSI and estimated PSI using fixed min/max values for the input parameters heart rate and skin temperature.

Method	Error on whole data			Error on valid data		
	M	SD	RMSE	M	SD	RMSE
PSI vs. estimated PSI (using PSI*)	1.764	2.303	2.900	0.883	0.575	1.054
PSI vs. estimated PSI (linear model)	1.587	1.476	2.167	1.026	0.640	1.209
PSI vs. estimated PSI (GPR model)	0.525	0.755	0.920	0.151	0.185	0.238

M=mean, SD=standard deviation

CONCLUSION AND FUTURE WORK

This work presented an attempt to develop and validate AI-based function approximators for a precise estimation of CBT and, finally, of the PSI, to enable accurate early alerts for physiological collapse. First results using GPR as a model for the estimation of CBT and PSI on field trial data of first responders, i.e., wildland firefighters, demonstrate that GPR appears to be a valuable ML design for this objective. In a future work, we will use heart rate variability (HRV), ambient temperature as well as humidity as additional input feature dimensions and validate if this could improve the results.

In the context of applying PSI for appropriate thresholding at the workplace, Davey et al. (2021) highlighted the relevance of hyperthermia-induced fatigue (HIF) as well as heat-related illnesses, both of which can be considered to cause an individual to reach a thermal tolerance limit. These issues are of a major concern to the industry as they can lead to accidents and absenteeism and can negatively affect the health and safety of workers (Flouris et al., 2018; Seppänen and Fisk, 2005). In this context, Davey et al. (2021) proposed to consider in addition a perception-based version of the PSI, i.e., PeSI by Tikuisis et al. (2002), replacing heart rate and core temperature with temperature sensation and RPE and using the upper limits of the perceptual scales (13 = intolerably hot and 10 = maximal exertion) as critical values.

The model for the development of the new AI-based estimator for physiological strain indexing was based on the knowledge about human physiology, in particular, physiological strain provided by Universidad de León, and the expertise on digital technologies including the development of the AI-based methodology was contributed by the JOANNEUM RESEARCH Forschungsgesellschaft mbH.

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