

Prototype of System to Identify Shape of Figure From Contour Drawn by Line of Sight

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ABSTRACT

In this study, we propose new input methods for users operating a computer with their gaze. The user traces the outline of a figure on the screen using their eyes. In addition to blinking and gazing, we believe these methods can serve as a form of gaze input. We prototyped a system in which eye movement data, captured while the user traces the outline of a shape on the screen with his/her gaze, is used to automatically identify the shape. We conducted an experiment to evaluate the system. The results showed that the system could accurately identify triangles as well as relatively large squares and circles on the screen. However, it struggled to accurately identify relatively small squares and circles.

Keywords: Figure identification, Line of sight, Gaze input, Machine learning

INTRODUCTION

Diseases such as amyotrophic lateral sclerosis restrict movement in only certain parts of the body. Patients with these diseases retain normal thinking ability, cognitive abilities and decision-making capacity, but their ability to express their intentions is diminished (Tetsuya et al., 2005). For instance, patients who cannot move their mouths cannot speak, and those who cannot move their fingers cannot write or operate a PC or smartphone. Eye gaze-based input systems have been developed as an alternative input method for PCs and smartphones. Current gaze input systems typically operate computers by varying the duration of gazing and blinking. These systems support two types of operations. Consider operating a smartphone using eye gaze-based input. While selecting an icon and performing tap operations are possible, existing gaze-based input methods do not support actions like flicking, pinching in, or pinching out. In addition to gazing and blinking, Kosaka et al. proposed a method in which users draw figures, such as circles and rectangles, on the screen using line of sight. For instance, if a user surrounds the icon with the line of sight and the trajectory of the line is square, the system interprets this as a flick gesture. This approach enables more types of operations using eye tracking. Kosaka et al. developed a prototype system to recognize figures on the basis of gaze trajectory data

using a probabilistic Hough transform. However, the system struggled with accurate figure recognition.

In this study, we developed and evaluated a prototype machine learning system to identify the type of figure drawn using eye tracking data. By leveraging machine learning, we aim to improve shape recognition accuracy, even when the gaze trajectory data contains significant noise or represents relatively complex shapes.

GRAPHIC IDENTIFICATION SYSTEM

Figure 1 shows the scheme and procedure of the graphic identification system. The system consists of two main components: image processing, which generates images from eye movement recording data, and shape classification model, which identifies the shape of the figure using machine learning.

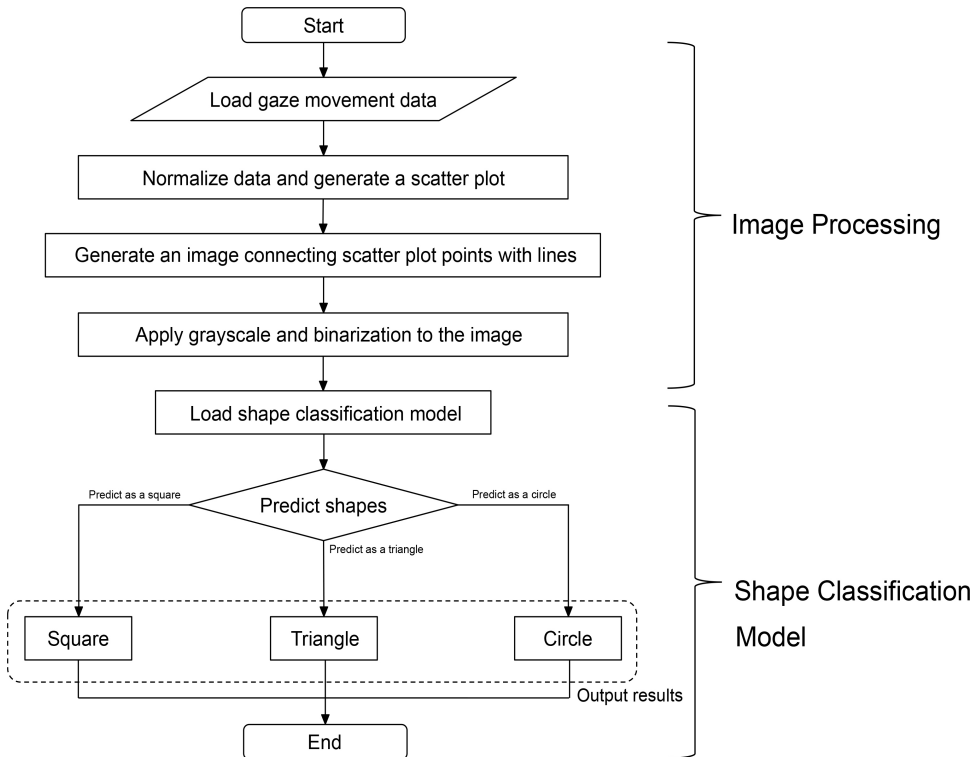


Figure 1: Scheme and procedure of graphic identification system.

Image Processing

The input data for this system consists of eye movement time-series data recorded while a participant looks at the computer screen. The eye movement data are captured as time-specific XY coordinates. For instance, when a participant traces the outline of a square with their gaze on the screen, a scatter plot, as shown in Figure 2(a), can be generated on the basis of the recorded XY coordinates. This scatter plot represents the contour of the gaze trajectory traced by the participant. The system then connects the points in

the scatter plot with straight lines to generate a black-and-white image, as shown in Figure 2(b). This image is used as training data to build the shape classification model.

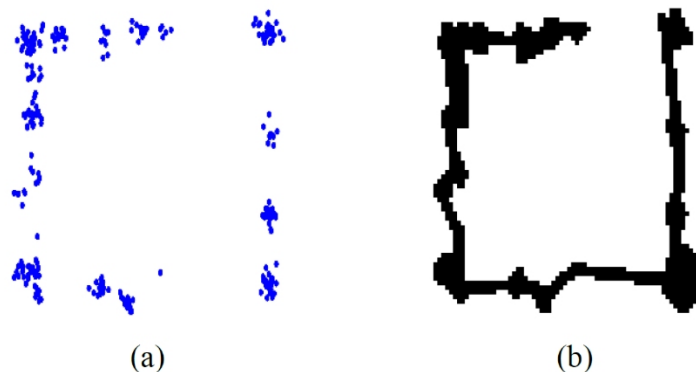


Figure 2: (a) Example of recorded gaze data when a participant traces the outline of a square on the screen, (b) generated black-and-white image of connected gaze data.

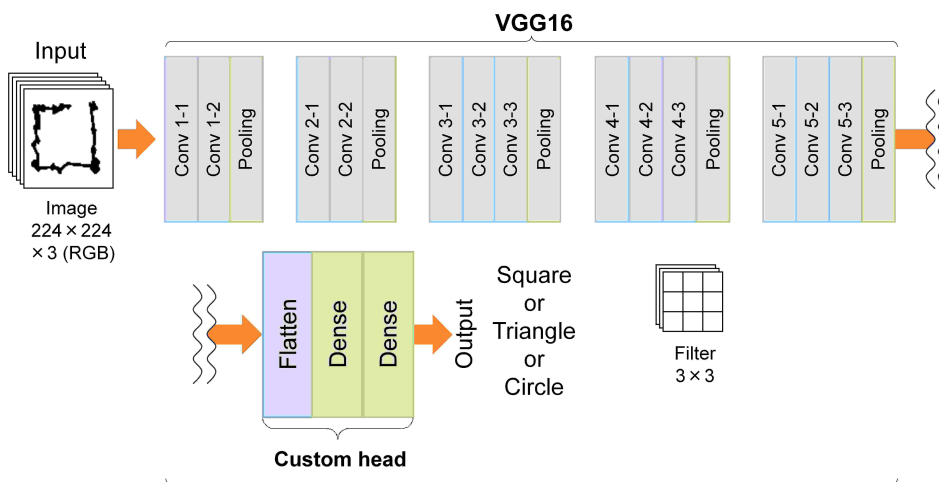


Figure 3: Composition of transfer learning model.

Shape Classification Model

Kosaka et al. recorded eye movement data while participants traced squares, triangles, and circles with their gaze on a computer screen. This data was used to train the system. We applied transfer learning (Toshihiro, 2010) to build the model. Figure 3 shows the structure of the transfer learning model for shape classification. We adopted VGG16 (Karen et al., 2015) as the pre-trained model. VGG16 consists of 13 convolutional layers alternating with 5 pooling layers, followed by 3 fully-connected layers at the end. We applied a custom head to this system that retains VGG16's feature

extraction capabilities while incorporating a new Flatten layer and two fully-connected layers. The system's input was a 224×224 pixel RGB image generated from eye movement data. The 3D tensor was converted into a 1D vector in the Flatten layer before being fed into the fully-connected layers. The first fully-connected layer contained 256 nodes and used a ReLU (Rectified Linear Unit) (Abien, 2019) activation function. The second fully-connected layer had three output nodes, corresponding to square, triangle, and circle classifications, and applied a softmax activation function (Bolin et al., 2018).

Apparatus

Table 1 shows the parameters of the transfer learning model we developed.

Table 1: Parameters of developed model.

Item	Details
Figure Type	Square, triangle and circle
Dataset	180 for training and 20 for evaluation in each figure
Data Argumentation	Random rotation within 25 degrees Horizontal and vertical inversion
Pre-trained Model	VCG16
Epoch	15
Batch Size	32
Image Size	224 square pixels
Convolutional Layer	13 layers
Pooling Layer	5 layers
Flatten Layer	1 layer
Hidden Layer	1 fully connected layer (dense layer), 256 neurons and ReLU activation function
Output Layer	1 fully connected layer (dense layer), 3 neurons and softmax activation function
Loss Function	Categorical cross-entropy
Optimizer	Adam (default setting)

Training Results

Figure 4 shows the loss and accuracy of the training dataset at each epoch. In epoch 14, the loss was extremely small at 0.00004117, and the accuracy reached its maximum value of 1.00. This high accuracy suggests that our model fits the training data well.

Next, we tested the model using a dataset not used during training. The model achieved a high accuracy of 0.9825. However, it should be noted that both the training and test data were collected from the same participants. Therefore, this evaluation may be insufficient to assess the model's generalizability.

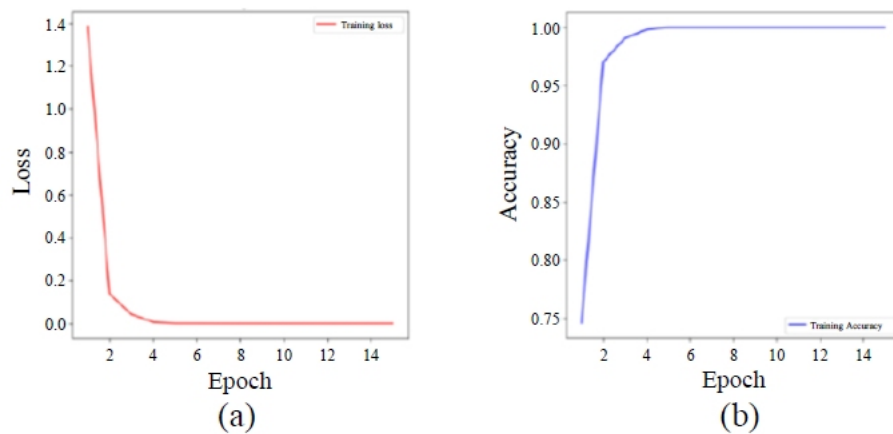


Figure 4: Loss (a) and accuracy (b) for training data set.

EXPERIMENT TO EVALUATE GRAPHIC IDENTIFICATION SYSTEM

We conducted an experiment to evaluate the prototyped shape identification model. In this experiment, we collected new eye movement data as participants traced shapes on the screen with their gaze. We input the data collected in this experiment into the graphic identification model and evaluated whether it could accurately identify the type of figure drawn from eye tracking data.

Procedure

The procedure for this experiment was as follows:

1. We explained the purpose of the experiment, the tasks participants would perform, and any potential risks. A total of 30 participants agreed to participate.
2. We calibrated the gaze measurement system for each participant to ensure accurate eye movement recording.
3. We displayed one of the figure images (square, triangle, or circle) from Figure 5 on a PC monitor.
4. Participants traced the outline of each shape, starting from the vertex marked with a black dot.
5. We recorded their eye movements.
6. Participants repeated steps 3 to 5 six times, tracing all six figures in Figure 5 with their gaze.
7. We inputted the eye movement data obtained in step 6 into the graphic identification system shown in Figure 1.
8. The system outputted the results of the shape identification.

Results

Table 2 shows the accuracy of the graphic identification system. The table shows that relatively large figures—Figure 5(a), (b), and (c)—all achieve an accuracy of over 95%. This indicates that the system can identify larger figures with high accuracy.

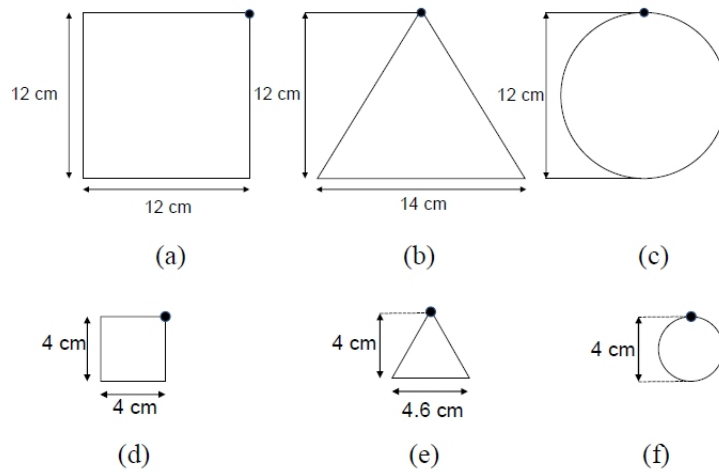


Figure 5: Figures participants looked at and traced on computer screen. Lengths in each figure indicate sizes when displayed on computer screen.

Table 2: Accuracy of the graphic identification system's output.

Figure Outline Participant Traced With Their Eyes	Accuracy [%]
Figure 5 (a) (Large Square)	95.0
Figure 5 (b) (Large Triangle)	98.3
Figure 5 (c) (Large Circle)	96.7
Figure 5 (d) (Small Square)	65.0
Figure 5 (e) (Small Triangle)	95.0
Figure 5 (f) (Small Circle)	73.3

Next, we focus on the type of figures. Table 2 shows that the accuracy for the relatively small square, Figure 5(d), is lower than that of the large one, Figure 5(a). A similar trend is observed when comparing the accuracy of the circles in Figures 5(c) and (f). However, no significant difference in accuracy was found between Figures 5(b) and (e).

Here, we consider why accuracy is unaffected by size for triangles. Figure 6(a) shows recorded gaze data from a participant tracing the outline of a square on the screen. This data contains outliers. We assume that outliers may arise from two possible causes: (1) the participant momentarily gazed at a location other than the intended contour, or (2) the gaze measurement device incorrectly detected the gaze point. The shape classification model tends to classify inputs such as those in Figure 6(b) as triangles. To improve the accuracy of for Figures 5(d) and (f) shown in Table 2, the noise similar to that as shown in Figure 6(b) should be removed before inputting it the data into the model. One possible improvement is to smooth the trajectory by connecting points with curves rather than straight lines when generating input images, as seen in Figure 6(b).

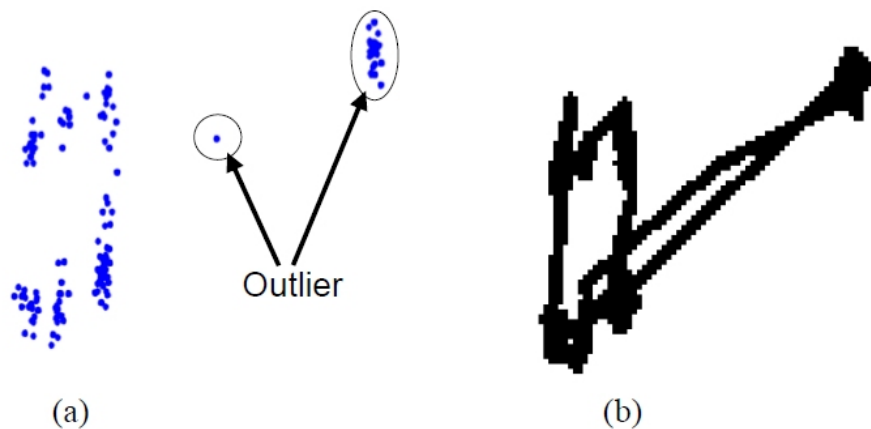


Figure 6: (a) Example of recorded gaze data when a participant traces the outline of a square on the screen. The data included outliers. (b) Generated black-and-white image of connected gaze data.

CONCLUSION

In this study, we proposed a new input method for operating a computer: tracing the outline of a figure on the screen with the user's eyes. We prototyped a system in which eye movement data is used as input when the user traces the outline of a shape on the screen with his/her gaze, and the system automatically identifies the shape. We conducted an experiment to evaluate the system. The results showed that the system could identify triangles, as well as relatively large squares and circles, with good accuracy. However, the system struggled to accurately identify relatively small squares and circles. Future research will focus on improving the accuracy of our system's shape identification, such as by removing noise from the input data.

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